## **Duality**

How do we get an upper bound to a maximization LP?

 $\max 13a + 23b$ s.t.  $5a + 15b \le 480$  $4a + 4b \le 160$  $35a + 20b \le 1190$  $a,b \geq 0$ 

Note that a lower bound is easy to derive. Every choice of  $a, b \ge 0$  gives us a lower bound (e.g. a = 12, b = 28 gives us a lower bound of 800).

If you take a conic combination of the rows (multiply the *i*-th row with  $y_i \ge 0$ ) such that  $\sum_i y_i a_{ii} \ge c_i$  then  $\sum_i y_i b_i$  will be an upper bound.

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## Duality

### Lemma 3

The dual of the dual problem is the primal problem.

### Proof:

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- $w = \min\{b^T \gamma \mid A^T \gamma \ge c, \gamma \ge 0\}$
- $w = -\max\{-b^T v \mid -A^T v \le -c, v \ge 0\}$

### The dual problem is

- ►  $z = -\min\{-c^T x \mid -Ax \ge -b, x \ge 0\}$
- $\blacktriangleright z = \max\{c^T x \mid Ax \le b, x \ge 0\}$

## **Duality**

### **Definition 2**

Let  $z = \max\{c^T x \mid Ax \le b, x \ge 0\}$  be a linear program *P* (called the primal linear program).

The linear program D defined by

$$w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$$

is called the dual problem.

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5.1 Weak Duality



5.1 Weak Duality

## **Weak Duality**

 $A^T \hat{y} \ge c \Rightarrow \hat{x}^T A^T \hat{y} \ge \hat{x}^T c \ (\hat{x} \ge 0)$ 

 $A\hat{x} \le b \Rightarrow y^T A\hat{x} \le \hat{y}^T b \ (\hat{y} \ge 0)$ 

This gives

$$c^T \hat{x} \le \hat{y}^T A \hat{x} \le b^T \hat{y}$$

Since, there exists primal feasible  $\hat{x}$  with  $c^T \hat{x} = z$ , and dual feasible  $\hat{y}$  with  $b^T y = w$  we get  $z \le w$ .

If P is unbounded then D is infeasible.

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## 5.2 Simplex and Duality

The following linear programs form a primal dual pair:

 $z = \max\{c^T x \mid Ax = b, x \ge 0\}$  $w = \min\{b^T y \mid A^T y \ge c\}$ 

This means for computing the dual of a standard form LP, we do not have non-negativity constraints for the dual variables.

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The following linear programs form a primal dual pair:

 $z = \max\{c^T x \mid Ax = b, x \ge 0\}$  $w = \min\{b^T y \mid A^T y \ge c\}$ 

This means for computing the dual of a standard form LP, we do not have non-negativity constraints for the dual variables.

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5.1 Weak Duality

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### Proof

### Primal:

$$\max\{c^{T}x \mid Ax = b, x \ge 0\}$$
  
=  $\max\{c^{T}x \mid Ax \le b, -Ax \le -b, x \ge 0\}$   
=  $\max\{c^{T}x \mid \begin{bmatrix} A \\ -A \end{bmatrix} x \le \begin{bmatrix} b \\ -b \end{bmatrix}, x \ge 0\}$ 

### Dual:

$$\min\{\begin{bmatrix} b^T & -b^T \end{bmatrix} y \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} y \ge c, y \ge 0\}$$
  
$$= \min\left\{\begin{bmatrix} b^T & -b^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \mid \begin{bmatrix} A^T & -A^T \end{bmatrix} \cdot \begin{bmatrix} y^+ \\ y^- \end{bmatrix} \ge c, y^- \ge 0, y^+ \ge 0\right\}$$
  
$$= \min\left\{b^T \cdot (y^+ - y^-) \mid A^T \cdot (y^+ - y^-) \ge c, y^- \ge 0, y^+ \ge 0\right\}$$
  
$$= \min\left\{b^T y' \mid A^T y' \ge c\right\}$$

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## **Proof of Optimality Criterion for Simplex**

Suppose that we have a basic feasible solution with reduced cost

 $\tilde{c} = c^T - c_B^T A_B^{-1} A \le 0$ 

This is equivalent to  $A^T (A_B^{-1})^T c_B \ge c$ 

 $y^* = (A_B^{-1})^T c_B$  is solution to the dual  $\min\{b^T y | A^T y \ge c\}$ .

$$b^{T} y^{*} = (Ax^{*})^{T} y^{*} = (A_{B}x_{B}^{*})^{T} y^{*}$$
  
=  $(A_{B}x_{B}^{*})^{T} (A_{B}^{-1})^{T} c_{B} = (x_{B}^{*})^{T} A_{B}^{T} (A_{B}^{-1})^{T} c_{B}$   
=  $c^{T}x^{*}$ 

5.2 Simplex and Duality

Hence, the solution is optimal.

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## **Strong Duality**

### **Theorem 6 (Strong Duality)**

Let P and D be a primal dual pair of linear programs, and let  $z^*$ and  $w^*$  denote the optimal solution to P and D, respectively. Then

 $z^* = w^*$ 



## **Proof of the Projection Lemma**

- Define f(x) = ||y x||.
- We want to apply Weierstrass but *X* may not be bounded.
- $X \neq \emptyset$ . Hence, there exists  $x' \in X$ .
- Define  $X' = \{x \in X \mid ||y x|| \le ||y x'||\}$ . This set is closed and bounded.
- Applying Weierstrass gives the existence.



### Lemma 8 (Projection Lemma)

Let  $X \subseteq \mathbb{R}^m$  be a non-empty convex set, and let  $y \notin X$ . Then there exist  $x^* \in X$  with minimum distance from y. Moreover for all  $x \in X$  we have  $(y - x^*)^T (x - x^*) \le 0$ .



## **Proof of the Projection Lemma (continued)**

 $x^*$  is minimum. Hence  $\|y - x^*\|^2 \le \|y - x\|^2$  for all  $x \in X$ .

By convexity:  $x \in X$  then  $x^* + \epsilon(x - x^*) \in X$  for all  $0 \le \epsilon \le 1$ .

$$\|y - x^*\|^2 \le \|y - x^* - \epsilon(x - x^*)\|^2$$
  
=  $\|y - x^*\|^2 + \epsilon^2 \|x - x^*\|^2 - 2\epsilon(y - x^*)^T (x - x^*)$ 

Hence,  $(y - x^*)^T (x - x^*) \le \frac{1}{2} \epsilon ||x - x^*||^2$ .

Letting  $\epsilon \rightarrow 0$  gives the result.

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### **Theorem 9 (Separating Hyperplane)**

Let  $X \subseteq \mathbb{R}^m$  be a non-empty closed convex set, and let  $y \notin X$ . Then there exists a separating hyperplane  $\{x \in \mathbb{R} : a^T x = \alpha\}$ where  $a \in \mathbb{R}^m$ ,  $\alpha \in \mathbb{R}$  that separates y from X.  $(a^T y < \alpha;$  $a^T x \ge \alpha$  for all  $x \in X$ )

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Lemma 10 (Farkas Lemma)

Let A be an  $m \times n$  matrix,  $b \in \mathbb{R}^m$ . Then exactly one of the following statements holds.

- **1.**  $\exists x \in \mathbb{R}^n$  with Ax = b,  $x \ge 0$
- **2.**  $\exists y \in \mathbb{R}^m$  with  $A^T y \ge 0$ ,  $b^T y < 0$

Assume  $\hat{x}$  satisfies 1. and  $\hat{y}$  satisfies 2. Then

 $0 > y^T b = y^T A x \ge 0$ 

Hence, at most one of the statements can hold.

## **Proof of the Hyperplane Lemma**

- Let  $x^* \in X$  be closest point to y in X.
- ▶ By previous lemma  $(y x^*)^T (x x^*) \le 0$  for all  $x \in X$ .
- Choose  $a = (x^* y)$  and  $\alpha = a^T x^*$ .
- For  $x \in X$ :  $a^T(x x^*) \ge 0$ , and, hence,  $a^T x \ge \alpha$ .
- Also,  $a^T y = a^T (x^* a) = \alpha ||a||^2 < \alpha$



## **Proof of Farkas Lemma**

Now, assume that 1. does not hold.

Consider  $S = \{Ax : x \ge 0\}$  so that *S* closed, convex,  $b \notin S$ .

We want to show that there is y with  $A^T y \ge 0$ ,  $b^T y < 0$ .

Let y be a hyperplane that separates b from S. Hence,  $y^T b < \alpha$ and  $y^T s \ge \alpha$  for all  $s \in S$ .

 $0 \in S \Rightarrow \alpha \le 0 \Rightarrow y^T b < 0$ 

 $y^T A x \ge \alpha$  for all  $x \ge 0$ . Hence,  $y^T A \ge 0$  as we can choose x arbitrarily large.

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### Lemma 11 (Farkas Lemma; different version)

Let A be an  $m \times n$  matrix,  $b \in \mathbb{R}^m$ . Then exactly one of the following statements holds.

- **1.**  $\exists x \in \mathbb{R}^n$  with  $Ax \le b$ ,  $x \ge 0$
- **2.**  $\exists y \in \mathbb{R}^m$  with  $A^T y \ge 0$ ,  $b^T y < 0$ ,  $y \ge 0$

### **Rewrite the conditions:**

**1.** 
$$\exists x \in \mathbb{R}^n$$
 with  $\begin{bmatrix} A \ I \end{bmatrix} \cdot \begin{bmatrix} x \\ s \end{bmatrix} = b, x \ge 0, s \ge 0$   
**2.**  $\exists y \in \mathbb{R}^m$  with  $\begin{bmatrix} A^T \\ I \end{bmatrix} y \ge 0, b^T y < 0$ 

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# Proof of Strong Duality

 $z \leq w$ : follows from weak duality

 $z \ge w$ :

We show  $z < \alpha$  implies  $w < \alpha$ .

$\exists x \in \mathbb{R}^n$				$\exists y \in \mathbb{R}^m; v \in \mathbb{R}$		
s.t.	Ax	$\leq$	b	s.t. $A^T y - c v$	$\geq$	0
	$Ax \\ -c^T x$	$\leq$	$-\alpha$	$b^T y - \alpha v$	<	0
	x	$\geq$	0	<i>y</i> , <i>v</i>	$\geq$	0

From the definition of  $\alpha$  we know that the first system is infeasible; hence the second must be feasible.

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## **Proof of Strong Duality**

 $P: z = \max\{c^T x \mid Ax \le b, x \ge 0\}$ 

 $D: w = \min\{b^T y \mid A^T y \ge c, y \ge 0\}$ 

### **Theorem 12 (Strong Duality)**

Let P and D be a primal dual pair of linear programs, and let z and w denote the optimal solution to P and D, respectively (i.e., P and D are non-empty). Then

	z = w.	
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Proof of Stro					
	$\exists y \in \mathbb{R}^m; v \in \mathbb{R}$ s.t.	• T			
	s.t.	$A^{T} \mathcal{Y} - \mathcal{V}$	≥	0	
		$b^T y - \alpha v$	<	0	
		<i>y</i> , <i>v</i>	$\geq$	0	
If the solution	n $y$ , $v$ has $v = 0$ w	ve have that			
	$\exists v \in \mathbb{R}^m$				
	s.t.	$A^T y \ge 0$			

is feasible. By Farkas lemma this gives that LP P is infeasible. Contradiction to the assumption of the lemma.

 $b^T y < 0$  $\gamma \ge 0$ 

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## **Proof of Strong Duality**

Hence, there exists a solution y, v with v > 0.

We can rescale this solution (scaling both y and v) s.t. v = 1.

Then y is feasible for the dual but  $b^T y < \alpha$ . This means that  $w < \alpha$ .

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## **Complementary Slackness**

### Lemma 14

Assume a linear program  $P = \max\{c^T x \mid Ax \le b; x \ge 0\}$  has solution  $x^*$  and its dual  $D = \min\{b^T y \mid A^T y \ge c; y \ge 0\}$  has solution  $y^*$ .

**1.** If  $x_i^* > 0$  then the *j*-th constraint in *D* is tight.

- **2.** If the *j*-th constraint in D is not tight than  $x_i^* = 0$ .
- **3.** If  $y_i^* > 0$  then the *i*-th constraint in *P* is tight.
- **4.** If the *i*-th constraint in *P* is not tight than  $y_i^* = 0$ .

If we say that a variable  $x_j^*$  ( $y_i^*$ ) has slack if  $x_j^* > 0$  ( $y_i^* > 0$ ), (i.e., the corresponding variable restriction is not tight) and a contraint has slack if it is not tight, then the above says that for a primal-dual solution pair it is not possible that a constraint **and** its corresponding (dual) variable has slack.

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## **Fundamental Questions**

### **Definition 13 (Linear Programming Problem (LP))**

Let  $A \in \mathbb{Q}^{m \times n}$ ,  $b \in \mathbb{Q}^m$ ,  $c \in \mathbb{Q}^n$ ,  $\alpha \in \mathbb{Q}$ . Does there exist  $x \in \mathbb{Q}^n$  s.t. Ax = b,  $x \ge 0$ ,  $c^T x \ge \alpha$ ?

### Questions:

- Is LP in NP?
- Is LP in co-NP? yes!
- Is LP in P?

### Proof:

- Given a primal maximization problem *P* and a parameter  $\alpha$ . Suppose that  $\alpha > \operatorname{opt}(P)$ .
- > We can prove this by providing an optimal basis for the dual.
- A verifier can check that the associated dual solution fulfills all dual constraints and that it has dual cost < α.</p>

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5.4 Strong Duality B

## **Proof: Complementary Slackness**

Analogous to the proof of weak duality we obtain

 $c^T x^* \le y^{*T} A x^* \le b^T y^*$ 

Because of strong duality we then get

$$c^T x^* = y^{*T} A x^* = b^T y^*$$

This gives e.g.

 $\sum_{j} (y^T A - c^T)_j x_j^* = 0$ 

From the constraint of the dual it follows that  $y^T A \ge c^T$ . Hence the left hand side is a sum over the product of non-negative numbers. Hence, if e.g.  $(y^T A - c^T)_j > 0$  (the *j*-th constraint in the dual is not tight) then  $x_j = 0$  (2.). The result for (1./3./4.) follows similarly.

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## **Interpretation of Dual Variables**

Brewer: find mix of ale and beer that maximizes profits

Entrepeneur: buy resources from brewer at minimum cost C, H, M: unit price for corn, hops and malt.

Note that brewer won't sell (at least not all) if e.g. 5C + 4H + 35M < 13 as then brewing ale would be advantageous.

## **Interpretation of Dual Variables**

If  $\epsilon$  is "small" enough then the optimum dual solution  $\gamma^*$  might not change. Therefore the profit increases by  $\sum_i \epsilon_i \gamma_i^*$ .

Therefore we can interpret the dual variables as marginal prices.

Note that with this interpretation, complementary slackness becomes obvious.

- If the brewer has slack of some resource (e.g. corn) then he is not willing to pay anything for it (corresponding dual variable is zero).
- If the dual variable for some resource is non-zero, then an increase of this resource increases the profit of the brewer. Hence, it makes no sense to have left-overs of this resource. Therefore its slack must be zero.

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5.5 Interpretation of Dual Variables

**Interpretation of Dual Variables** 

### **Marginal Price:**

- How much money is the brewer willing to pay for additional amount of Corn, Hops, or Malt?
- We are interested in the marginal price, i.e., what happens if we increase the amount of Corn, Hops, and Malt by ε<sub>C</sub>, ε<sub>H</sub>, and ε<sub>M</sub>, respectively.

The profit increases to  $\max\{c^T x \mid Ax \le b + \varepsilon; x \ge 0\}$ . Because of strong duality this is equal to

	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	
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Of course, the previous argument about the increase in the primal objective only holds for the non-degenerate case.

If the optimum basis is degenerate then increasing the supply of one resource may not allow the objective value to increase.

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**Flows** 

Definition 16

The value of an (s, t)-flow f is defined as

$$\operatorname{val}(f) = \sum_{X} f_{SX} - \sum_{X} f_{XS} .$$

**Maximum Flow Problem:** Find an (s, t)-flow with maximum value.

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5.5 Interpretation of Dual Variables

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### **Flows**

### **Definition 15**

An (s, t)-flow in a (complete) directed graph  $G = (V, V \times V, c)$  is a function  $f : V \times V \mapsto \mathbb{R}_0^+$  that satisfies

**1.** For each edge (x, y)

$$0 \leq f_{XY} \leq c_{XY} \ .$$

(capacity constraints)

**2.** For each  $v \in V \setminus \{s, t\}$ 

$$\sum_{x} f_{vx} = \sum_{x} f_{xv} \; .$$

(flow conservation constraints)

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5.5 Interpretation of Dual Variables







The value  $p_x$  for a variable, then can be seen as the distance of x to t (where the distance from s to t is required to be 1 since  $p_s = 1$ ).

The constraint  $p_x \leq \ell_{xy} + p_y$  then simply follows from triangle inequality  $(d(x,t) \leq d(x,y) + d(y,t) \Rightarrow d(x,t) \leq \ell_{xy} + d(y,t))$ .

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LP-Formu	lation	of	Maxflow
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	min		$\sum_{(xy)} c_{xy} \ell_{xy}$				
	s.t.	$f_{xy}(x, y \neq s, t)$ :	$1\ell_{xy}-1p_x+1p_y \ge$	0			
		$f_{sy}(y \neq s,t)$ :	$1\ell_{sy} - p_s + 1p_y \ge$	0			
		$f_{xs}$ $(x \neq s, t)$ :	$1\ell_{xs}-1p_x+p_s \geq$	0			
		$f_{ty} (y \neq s, t)$ :	$1\ell_{ty} - p_t + 1p_y \ge$	0			
		$f_{xt}$ $(x \neq s, t)$ :	$1\ell_{xt}-1p_x+p_t \geq$	0			
		$f_{st}$ :	$1\ell_{st}-p_s+p_t \geq$	0			
		$f_{ts}$ :	$1\ell_{ts}-p_t+p_s \geq$	0			
			$\ell_{xy} \geq$	0			
with $p_t = 0$ and $p_s = 1$ .							
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One can show that there is an optimum LP-solution for the dual problem that gives an integral assignment of variables.

This means  $p_{\chi} = 1$  or  $p_{\chi} = 0$  for our case. This gives rise to a cut in the graph with vertices having value 1 on one side and the other vertices on the other side. The objective function then evaluates the capacity of this cut.

This shows that the Maxflow/Mincut theorem follows from linear programming duality.

### **Flows**

**Definition 17** 

An (s, t)-flow in a (complete) directed graph  $G = (V, V \times V, c)$  is a function  $f : V \times V \mapsto \mathbb{R}_0^+$  that satisfies

**1.** For each edge (x, y)

$$0 \leq f_{XY} \leq c_{XY} \ .$$

(capacity constraints)

**2.** For each  $v \in V \setminus \{s, t\}$ 

$$\sum_{x} f_{vx} = \sum_{x} f_{xv} \; .$$

(flow conservation constraints)

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max 2	$\sum_{z} f_{sz} - \sum_{z} f_{zs}$
s.t. $\forall (z, w) \in V \times V$	$f_{zw} \leq c_{zw}$
$\forall w \neq s, t  \sum_{k=1}^{\infty} dk = \sum_{k=1}^{\infty} dk = k $	$f_{zw} - \sum_{z} f_{wz} = 0 \qquad 1$
	$f_{zw} \geq 0$
min	$\sum_{(xy)} c_{xy} \ell_{xy}$
	$\frac{\mathcal{L}(xy)}{\mathcal{L}(xy)} \frac{\mathcal{L}(xy)}{\mathcal{L}(xy)} \frac{\mathcal{L}(xy)}{\mathcal{L}(xy)} \geq 0$
	$1\ell_{sy}$ $+1p_{y} \ge 1$
$f_{xs} (x \neq s, t):$	$1\ell_{xs}-1p_x \geq -1$
$f_{ty} (y \neq s, t)$ :	$1\ell_{ty} + 1p_{y} \ge 0$
$f_{xt}$ ( $x \neq s, t$ ):	$1\ell_{xt} - 1p_x \ge 0$
$f_{st}$ :	$1\ell_{st} \geq 1$
0	$1\ell_{ts} \geq -1$
515	$\ell_{XV} \ge 0$
	$v_{XY} \geq 0$

## **Flows**

### **Definition 18**

The value of an (s, t)-flow f is defined as

$$\operatorname{val}(f) = \sum_{x} f_{sx} - \sum_{x} f_{xs} \; .$$

**Maximum Flow Problem:** Find an (s, t)-flow with maximum value.

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5.6 Computing Duals





One can show that there is an optimum LP-solution for the dual problem that gives an integral assignment of variables.

This means  $p_x = 1$  or  $p_x = 0$  for our case. This gives rise to a cut in the graph with vertices having value 1 on one side and the other vertices on the other side. The objective function then evaluates the capacity of this cut.

This shows that the Maxflow/Mincut theorem follows from linear programming duality.

## **LP-Formulation of Maxflow**

min		$\sum_{(xy)} c_{xy} \ell_{xy}$		
s.t.	$f_{xy}$ :	$1\ell_{xy}-1p_x+1p_y$	$\geq$	0
		$\ell_{xy}$	$\geq$	0
		$p_s$	=	1
		$p_t$	=	0

We can interpret the  $\ell_{xy}$  value as assigning a length to every edge.

The value  $p_x$  for a variable, then can be seen as the distance of x to t (where the distance from s to t is required to be 1 since  $p_s = 1$ ).

The constraint  $p_x \leq \ell_{xy} + p_y$  then simply follows from triangle inequality  $(d(x,t) \leq d(x,y) + d(y,t) \Rightarrow d(x,t) \leq \ell_{xy} + d(y,t))$ .

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5.6 Computing Duals



