Wintersemester 2014/15

## Selected Topics in Efficient Algorithms

http://www14.in.tum.de/lehre/2014WS/

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#### Organization



Seminar Sessions:

2 SWS Mon 14:00–16:00, MI 03.11.018

Duties:

Presentation of 60 minutes

Write-up of 8 to 10 pages

# 1. Computational geometry: Convex hulls



M. De Berg, O. Cheong, M. van Kreveld, M. Overmars. Computational Geometry. Chapter 1 & 11.

# 2. Comp. geometry: Line segment intersection



M. De Berg, O. Cheong, M. van Kreveld, M. Overmars. Computational Geometry. Chapter 2.

### 3. Comp. geometry: Voronoi diagrams



M. De Berg, O. Cheong, M. van Kreveld, M. Overmars. Computational Geometry. Chapter 7.

### 4. Scheduling: Makespan minimzation



m identical parallel machines

Input portion: Job J<sub>i</sub> with individual processing time p<sub>i</sub>.

Goal: Minimize the completion time of the last job in the schedule.

R. Graham. Bell Systems Techn. Journal 1965; SIAM J. Applied Math., 1969.

#### 5.Scheduling: Load balancing game



Each job controlled by selfish agent.

Cost of an agent is the load of the selected machine.

Social cost: Makespan of the solution.

B. Vöcking. In: Algorithmic Game Theory, Chapter 20, 2007.

#### 6.Scheduling: Story boarding





A. Dasgupta, A. Ghosh, H. Nazerzadeh, P. Raghavan SODA 2009. S. Albers, A. Passen, ICALP 2013.

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#### 7. Data structures: List update

**Unsorted linear list** 



 $\sigma = AACBEDA \dots$ 

Request: Access to item in the list

Cost: Accessing the i-th item in the list incurs a cost of i.

Goal: Minimize cost paid in serving  $\sigma$ .

Applications: Data compression

S. Albers, S. Lauer. On list update with locality of reference. ICALP 2008.

#### 8. Network design: Fair cost allocation



G=(V,E,c) pairs  $(s_i,t_i)$  If k agents use e, each pays c(e)/k

Anshlevich, Dasgupta, Kleinberg, Tardos, Wexler. SICOMP 2008.

#### 9. Network design: Arbitrary payments



G=(V,E,c) pairs  $(s_i,t_i)$  Cost of an edge may be split arbitrarily.

Anshlevich, Dasgupta, Tardos, Wexler. Theory of Computing, 2008.

#### 10. Routing: Energy optimization





G=(V,E) pairs (s<sub>i</sub>,t<sub>i</sub>) min  $\Sigma_e$  f(l<sub>e</sub>) where f(l) = c + l<sup> $\alpha$ </sup>

Andrew, Antonakopoulos, Zhang, Min-cost network design with dis-(economies) of scale. FOCS 2010. WS 2014/15