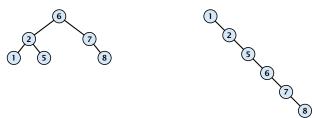
7.1 Binary Search Trees

An (internal) binary search tree stores the elements in a binary tree. Each tree-node corresponds to an element. All elements in the left sub-tree of a node v have a smaller key-value than $\ker[v]$ and elements in the right sub-tree have a larger-key value. We assume that all key-values are different.

(External Search Trees store objects only at leaf-vertices)

Examples:

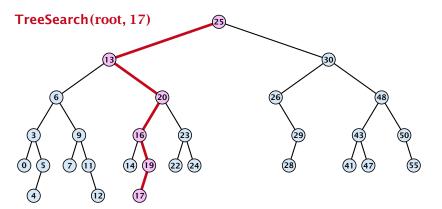


7.1 Binary Search Trees

We consider the following operations on binary search trees. Note that this is a super-set of the dictionary-operations.

- ightharpoonup T. insert(x)
- ightharpoonup T. delete(x)
- ightharpoonup T. search(k)
- ightharpoonup T. successor(x)
- ► *T*. predecessor(*x*)
- ightharpoonup T. minimum()
- ightharpoonup T. maximum()

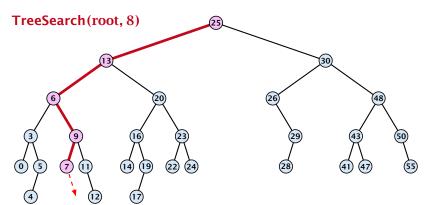
Binary Search Trees: Searching



Algorithm 5 TreeSearch(x, k)

- 1: **if** x = null or k = key[x] **return** x
- 2: **if** k < key[x] **return** TreeSearch(left[x], k)
- 3: **else return** TreeSearch(right[x], k)

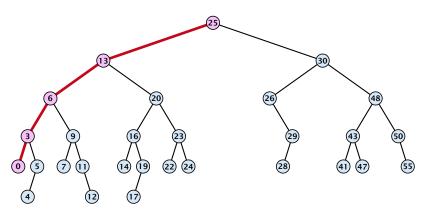
Binary Search Trees: Searching



Algorithm 5 TreeSearch(x, k)

- 1: **if** x = null or k = key[x] **return** x
- 2: **if** k < key[x] **return** TreeSearch(left[x], k)
- 3: **else return** TreeSearch(right[x], k)

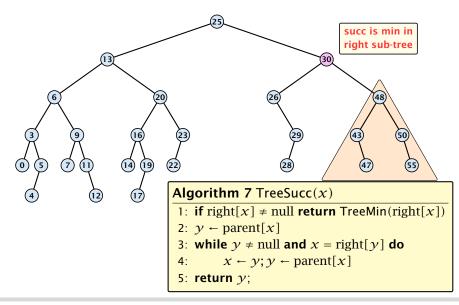
Binary Search Trees: Minimum



Algorithm 6 TreeMin(x)

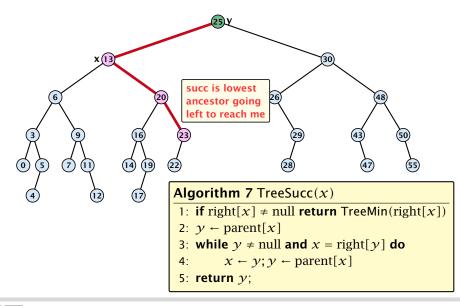
- 1: **if** x = null or left[x] = null return x
- 2: **return** TreeMin(left[x])

Binary Search Trees: Successor





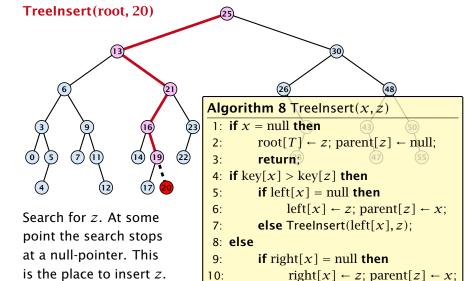
Binary Search Trees: Successor





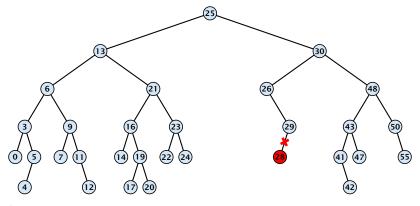
Binary Search Trees: Insert

Insert element **not** in the tree.



11:

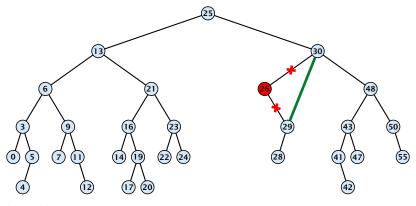
else TreeInsert(right[x], z);



Case 1:

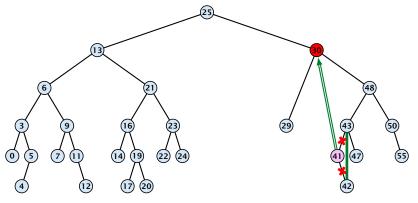
Element does not have any children

Simply go to the parent and set the corresponding pointer to null.



Case 2: Element has exactly one child

Splice the element out of the tree by connecting its parent to its successor.



Case 3: Flement has two children

- Find the successor of the element
- Splice successor out of the tree
- Replace content of element by content of successor

```
Algorithm 9 TreeDelete(z)
 1: if left[z] = null or right[z] = null
         then y \leftarrow z else y \leftarrow \text{TreeSucc}(z); select y to splice out
 3: if left[\gamma] \neq null
         then x \leftarrow \text{left}[y] else x \leftarrow \text{right}[y]; x is child of y (or null)
 5: if x \neq \text{null then parent}[x] \leftarrow \text{parent}[y]; parent[x] is correct
 6: if parent[\gamma] = null then
 7: root[T] \leftarrow x
 8: else
 9: if y = left[parent[y]] then
                                                                 fix pointer to x
10: \operatorname{left}[\operatorname{parent}[y]] \leftarrow x
11: else
        right[parent[y]] \leftarrow x
13: if y \neq z then copy y-data to z
```

Balanced Binary Search Trees

All operations on a binary search tree can be performed in time $\mathcal{O}(h)$, where h denotes the height of the tree.

However the height of the tree may become as large as $\Theta(n)$.

Balanced Binary Search Trees

With each insert- and delete-operation perform local adjustments to guarantee a height of $\mathcal{O}(\log n)$.

AVL-trees, Red-black trees, Scapegoat trees, 2-3 trees, B-trees, AA trees, Treaps

similar: SPLAY trees.

Binary Search Trees (BSTs)

Bibliography

[MS08] Kurt Mehlhorn, Peter Sanders:

Algorithms and Data Structures — The Basic Toolbox,

Springer, 2008

[CLRS90] Thomas H. Cormen, Charles E. Leiserson, Ron L. Rivest, Clifford Stein:

Introduction to Algorithms (3rd ed.),

MIT Press and McGraw-Hill, 2009

Binary search trees can be found in every standard text book. For example Chapter 7.1 in [MS08] and Chapter 12 in [CLRS90].