#### How to choose augmenting paths?

- ► We need to find paths efficiently.
- We want to guarantee a small number of iterations.

### Several possibilities:

- Choose path with maximum bottleneck capacity.
- Choose path with sufficiently large bottleneck capacity.
- Choose the shortest augmenting path.

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Algorithm 45 maxflow( $G, s, t, c$ )
1: foreach $e \in E$ do $f_e \leftarrow 0$ ;
2: $\Delta \leftarrow 2^{\lceil \log_2 C \rceil}$
3: while $\Delta \ge 1$ do
4: $G_f(\Delta) \leftarrow \Delta$ -residual graph
5: while there is augmenting path $P$ in $G_f(\Delta)$ do
6: $f \leftarrow \operatorname{augment}(f, c, P)$
6: $f \leftarrow \operatorname{augment}(f, c, P)$ 7: $\operatorname{update}(G_f(\Delta))$ 8: $\Delta \leftarrow \Delta/2$
8: $\Delta \leftarrow \Delta/2$
9: <b>return</b> <i>f</i>

## **Capacity Scaling**

### Intuition:

- Choosing a path with the highest bottleneck increases the flow as much as possible in a single step.
- Don't worry about finding the exact bottleneck.
- Maintain scaling parameter  $\Delta$ .
- $G_f(\Delta)$  is a sub-graph of the residual graph  $G_f$  that contains only edges with capacity at least  $\Delta$ .



## **Capacity Scaling**

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#### Assumption:

All capacities are integers between 1 and C.

#### Invariant:

All flows and capacities are/remain integral throughout the algorithm.

#### Correctness:

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The algorithm computes a maxflow:

- because of integrality we have  $G_f(1) = G_f$
- therefore after the last phase there are no augmenting paths anymore

12.3 Capacity Scaling

this means we have a maximum flow.

## **Capacity Scaling**

**Lemma 1** *There are*  $\lceil \log C \rceil$  *iterations over*  $\Delta$ *.* **Proof:** obvious.

#### Lemma 2

Let f be the flow at the end of a  $\Delta$ -phase. Then the maximum flow is smaller than  $val(f) + 2m\Delta$ .

**Proof:** less obvious, but simple:

- There must exist an *s*-*t* cut in  $G_f(\Delta)$  of zero capacity.
- in  $G_f$  this cut can have capacity at most  $2m\Delta$ .
- This gives me an upper bound on the flow that I can still add.

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# **Capacity Scaling**

## Lemma 3

There are at most 2m augmentations per scaling-phase.

### Proof:

- Let *f* be the flow at the end of the previous phase.
- $\operatorname{val}(f^*) \leq \operatorname{val}(f) + 2m\Delta$
- each augmentation increases flow by  $\Delta$ .

#### **Theorem 4**

We need  $O(m \log C)$  augmentations. The algorithm can be implemented in time  $O(m^2 \log C)$ .

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