

## 7.7 Hashing

### Dictionary:

- ▶ **S.insert( $x$ )**: Insert an element  $x$ .
- ▶ **S.delete( $x$ )**: Delete the element pointed to by  $x$ .
- ▶ **S.search( $k$ )**: Return a pointer to an element  $e$  with  $\text{key}[e] = k$  in  $S$  if it exists; otherwise return null.

So far we have implemented the search for a key by carefully choosing split-elements.

Then the memory location of an object  $x$  with key  $k$  is determined by successively comparing  $k$  to split-elements.

Hashing tries to **directly** compute the memory location from the given key. The goal is to have constant search time.

## 7.7 Hashing

### Definitions:

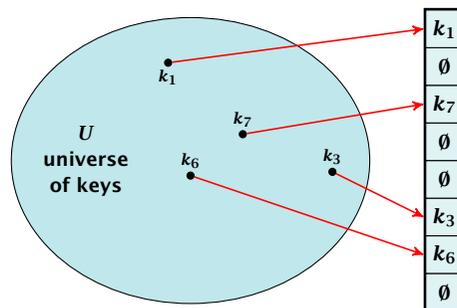
- ▶ Universe  $U$  of keys, e.g.,  $U \subseteq \mathbb{N}_0$ .  $U$  very large.
- ▶ Set  $S \subseteq U$  of keys,  $|S| = m \leq n$ .
- ▶ Array  $T[0, \dots, n-1]$  hash-table.
- ▶ Hash function  $h : U \rightarrow [0, \dots, n-1]$ .

### The hash-function $h$ should fulfill:

- ▶ Fast to evaluate.
- ▶ Small storage requirement.
- ▶ Good distribution of elements over the whole table.

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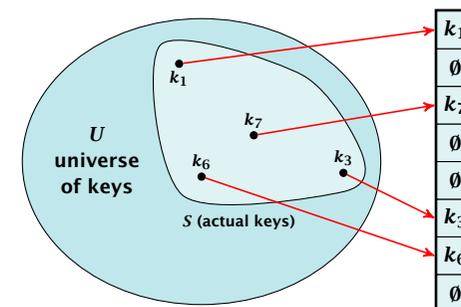
Ideally the hash function maps **all** keys to different memory locations.



This special case is known as **Direct Addressing**. It is usually very unrealistic as the universe of keys typically is quite large, and in particular larger than the available memory.

## 7.7 Hashing

Suppose that we **know** the set  $S$  of actual keys (no insert/no delete). Then we may want to design a **simple** hash-function that maps all these keys to different memory locations.



Such a hash function  $h$  is called a **perfect hash function** for set  $S$ .

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If we do not know the keys in advance, the best we can hope for is that the hash function distributes keys evenly across the table.

### Problem: Collisions

Usually the universe  $U$  is much larger than the table-size  $n$ .

Hence, there may be two elements  $k_1, k_2$  from the set  $S$  that map to the same memory location (i.e.,  $h(k_1) = h(k_2)$ ). This is called a **collision**.

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Typically, collisions do not appear once the size of the set  $S$  of actual keys gets close to  $n$ , but already once  $|S| \geq \omega(\sqrt{n})$ .

### Lemma 21

The probability of having a collision when hashing  $m$  elements into a table of size  $n$  under uniform hashing is at least

$$1 - e^{-\frac{m(m-1)}{2}} \approx 1 - e^{-\frac{m^2}{2n}}.$$

### Uniform hashing:

Choose a hash function uniformly at random from all functions  $f: U \rightarrow [0, \dots, n-1]$ .

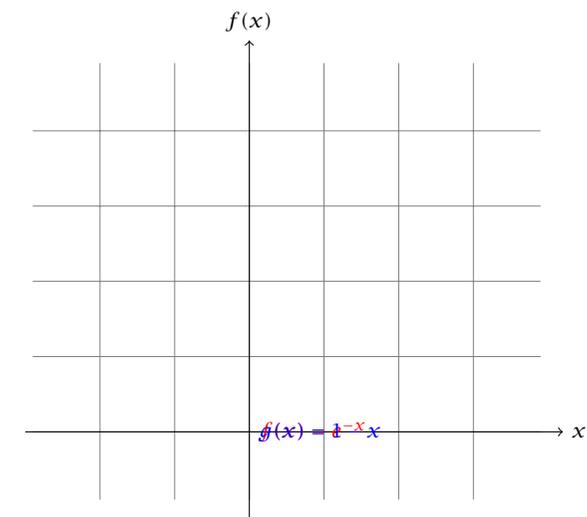
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### Proof.

Let  $A_{m,n}$  denote the event that inserting  $m$  keys into a table of size  $n$  does **not** generate a collision. Then

$$\begin{aligned} \Pr[A_{m,n}] &= \prod_{\ell=1}^m \frac{n - \ell + 1}{n} = \prod_{j=0}^{m-1} \left(1 - \frac{j}{n}\right) \\ &\leq \prod_{j=0}^{m-1} e^{-j/n} = e^{-\sum_{j=0}^{m-1} \frac{j}{n}} = e^{-\frac{m(m-1)}{2n}}. \end{aligned}$$

Here the first equality follows since the  $\ell$ -th element that is hashed has a probability of  $\frac{n-\ell+1}{n}$  to not generate a collision under the condition that the previous elements did not induce collisions.  $\square$



The inequality  $1 - x \leq e^{-x}$  is derived by stopping the Taylor-expansion of  $e^{-x}$  after the second term.

## Resolving Collisions

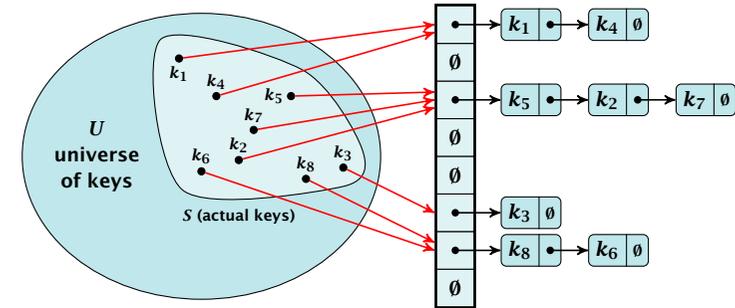
The methods for dealing with collisions can be classified into the two main types

- ▶ **open addressing**, aka. closed hashing
- ▶ **hashing with chaining**, aka. closed addressing, open hashing.

## Hashing with Chaining

Arrange elements that map to the same position in a linear list.

- ▶ Access: compute  $h(x)$  and search list for  $\text{key}[x]$ .
- ▶ Insert: insert at the front of the list.



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Let  $A$  denote a strategy for resolving collisions. We use the following notation:

- ▶  $A^+$  denotes the average time for a **successful** search when using  $A$ ;
- ▶  $A^-$  denotes the average time for an **unsuccessful** search when using  $A$ ;
- ▶ We parameterize the complexity results in terms of  $\alpha := \frac{m}{n}$ , the so-called **fill factor** of the hash-table.

We assume **uniform hashing** for the following analysis.

## Hashing with Chaining

The time required for an unsuccessful search is 1 plus the length of the list that is examined. The average length of a list is  $\alpha = \frac{m}{n}$ . Hence, if  $A$  is the collision resolving strategy “Hashing with Chaining” we have

$$A^- = 1 + \alpha .$$

Note that this result does not depend on the hash-function that is used.

## Hashing with Chaining

For a successful search observe that we do **not** choose a list at random, but we consider a random key  $k$  in the hash-table and ask for the search-time for  $k$ .

This is 1 plus the number of elements that lie before  $k$  in  $k$ 's list.

Let  $k_\ell$  denote the  $\ell$ -th key inserted into the table.

Let for two keys  $k_i$  and  $k_j$ ,  $X_{ij}$  denote the event that  $i$  and  $j$  hash to the same position. Clearly,  $\Pr[X_{ij} = 1] = 1/n$  for uniform hashing.

The expected successful search cost is

$$E \left[ \frac{1}{m} \sum_{i=1}^m \left( 1 + \sum_{j=i+1}^m X_{ij} \right) \right]$$

keys before  $k_i$   
cost for key  $k_i$

## Hashing with Chaining

$$\begin{aligned} E \left[ \frac{1}{m} \sum_{i=1}^m \left( 1 + \sum_{j=i+1}^m X_{ij} \right) \right] &= \frac{1}{m} \sum_{i=1}^m \left( 1 + \sum_{j=i+1}^m E[X_{ij}] \right) \\ &= \frac{1}{m} \sum_{i=1}^m \left( 1 + \sum_{j=i+1}^m \frac{1}{n} \right) \\ &= 1 + \frac{1}{mn} \sum_{i=1}^m (m-i) \\ &= 1 + \frac{1}{mn} \left( m^2 - \frac{m(m+1)}{2} \right) \\ &= 1 + \frac{m-1}{2n} = 1 + \frac{\alpha}{2} - \frac{\alpha}{2m} . \end{aligned}$$

Hence, the expected cost for a successful search is  $A^+ \leq 1 + \frac{\alpha}{2}$ .

## Open Addressing

All objects are stored in the table itself.

Define a function  $h(k, j)$  that determines the table-position to be examined in the  $j$ -th step. The values  $h(k, 0), \dots, h(k, n-1)$  form a permutation of  $0, \dots, n-1$ .

**Search( $k$ ):** Try position  $h(k, 0)$ ; if it is empty your search fails; otw. continue with  $h(k, 1), h(k, 2), \dots$

**Insert( $x$ ):** Search until you find an empty slot; insert your element there. If your search reaches  $h(k, n-1)$ , and this slot is non-empty then your table is full.

## Open Addressing

Choices for  $h(k, j)$ :

- ▶  $h(k, i) = h(k) + i \pmod n$ . Linear probing.
- ▶  $h(k, i) = h(k) + c_1 i + c_2 i^2 \pmod n$ . Quadratic probing.
- ▶  $h(k, i) = h_1(k) + i h_2(k) \pmod n$ . Double hashing.

For quadratic probing and double hashing one has to ensure that the search covers all positions in the table (i.e., for double hashing  $h_2(k)$  must be relatively prime to  $n$ ; for quadratic probing  $c_1$  and  $c_2$  have to be chosen carefully).

## Linear Probing

- ▶ Advantage: **Cache-efficiency**. The new probe position is very likely to be in the cache.
- ▶ Disadvantage: **Primary clustering**. Long sequences of occupied table-positions get longer as they have a larger probability to be hit. Furthermore, they can merge forming larger sequences.

### Lemma 22

Let  $L$  be the method of linear probing for resolving collisions:

$$L^+ \approx \frac{1}{2} \left( 1 + \frac{1}{1 - \alpha} \right)$$
$$L^- \approx \frac{1}{2} \left( 1 + \frac{1}{(1 - \alpha)^2} \right)$$

## Quadratic Probing

- ▶ Not as cache-efficient as Linear Probing.
- ▶ **Secondary clustering**: caused by the fact that all keys mapped to the same position have the same probe sequence.

### Lemma 23

Let  $Q$  be the method of quadratic probing for resolving collisions:

$$Q^+ \approx 1 + \ln \left( \frac{1}{1 - \alpha} \right) - \frac{\alpha}{2}$$
$$Q^- \approx \frac{1}{1 - \alpha} + \ln \left( \frac{1}{1 - \alpha} \right) - \alpha$$

## Double Hashing

- ▶ Any probe into the hash-table usually creates a cash-miss.

### Lemma 24

Let  $A$  be the method of double hashing for resolving collisions:

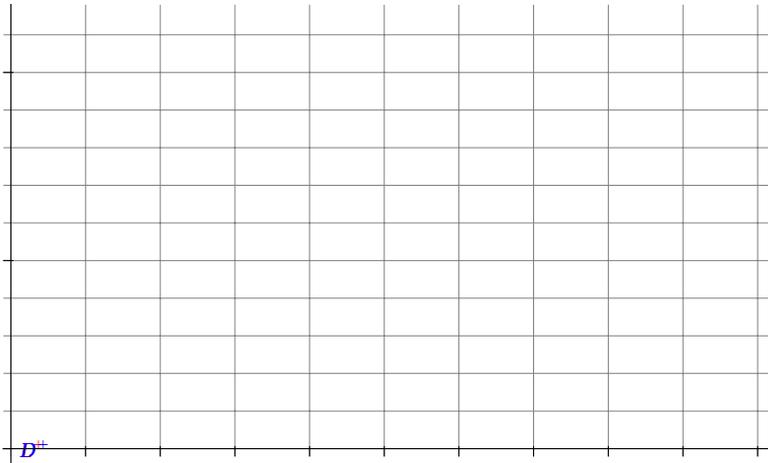
$$D^+ \approx \frac{1}{\alpha} \ln \left( \frac{1}{1 - \alpha} \right)$$
$$D^- \approx \frac{1}{1 - \alpha}$$

## 7.7 Hashing

### Some values:

$\alpha$	Linear Probing		Quadratic Probing		Double Hashing	
	$L^+$	$L^-$	$Q^+$	$Q^-$	$D^+$	$D^-$
0.5	1.5	2.5	1.44	2.19	1.39	2
0.9	5.5	50.5	2.85	11.40	2.55	10
0.95	10.5	200.5	3.52	22.05	3.15	20

## 7.7 Hashing



## Analysis of Idealized Open Address Hashing

Let  $X$  denote a random variable describing the number of probes in an **unsuccessful** search.

Let  $A_i$  denote the event that the  $i$ -th probe occurs and is to a non-empty slot.

$$\begin{aligned} \Pr[A_1 \cap A_2 \cap \dots \cap A_{i_1}] \\ = \Pr[A_1] \cdot \Pr[A_2 \mid A_1] \cdot \Pr[A_3 \mid A_1 \cap A_2] \cdot \\ \dots \cdot \Pr[A_{i_1} \mid A_1 \cap \dots \cap A_{i-2}] \end{aligned}$$

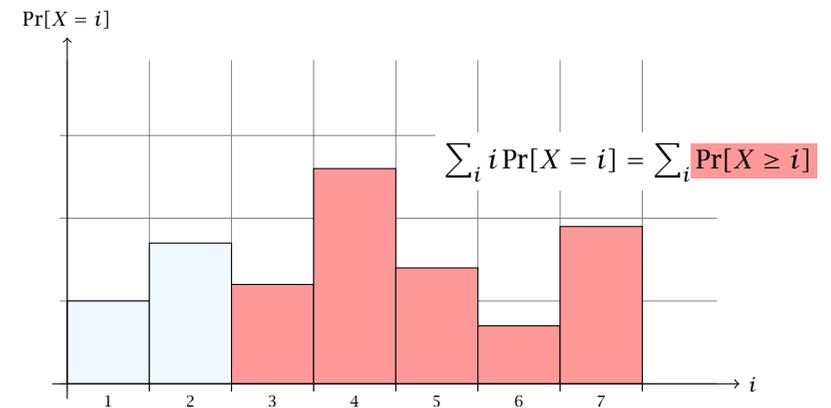
$$\begin{aligned} \Pr[X \geq i] &= \frac{m}{n} \cdot \frac{m-1}{n-1} \cdot \frac{m-2}{n-2} \cdot \dots \cdot \frac{m-i+2}{n-i+2} \\ &\leq \left(\frac{m}{n}\right)^{i-1} = \alpha^{i-1}. \end{aligned}$$

## Analysis of Idealized Open Address Hashing

$$E[X] = \sum_{i=1}^{\infty} \Pr[X \geq i] \leq \sum_{i=1}^{\infty} \alpha^{i-1} = \sum_{i=0}^{\infty} \alpha^i = \frac{1}{1-\alpha}.$$

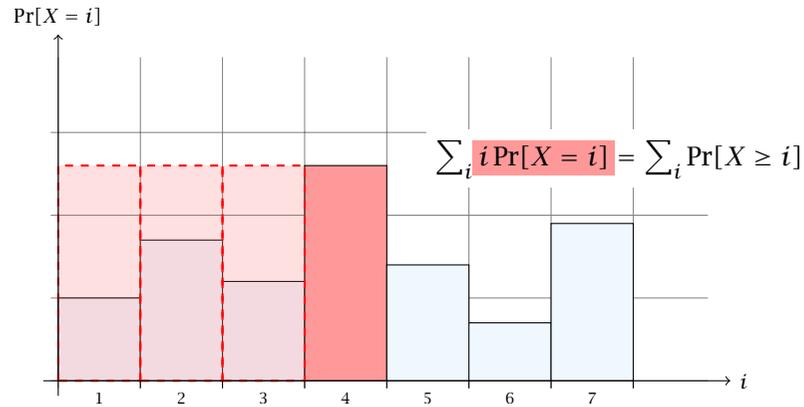
$$\frac{1}{1-\alpha} = 1 + \alpha + \alpha^2 + \alpha^3 + \dots$$

$i = 3$



The  $j$ -th rectangle appears in both sums  $j$  times. ( $j$  times in the first due to multiplication with  $j$ ; and  $j$  times in the second for summands  $i = 1, 2, \dots, j$ )

$i = 4$



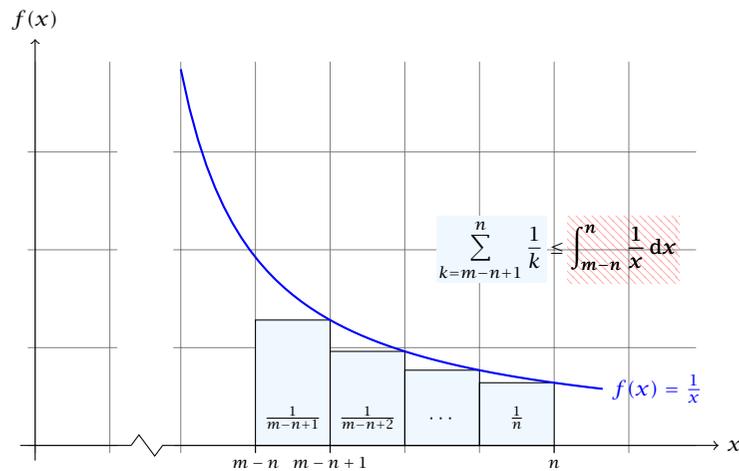
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## Analysis of Idealized Open Address Hashing

The number of probes in a **successful** for  $k$  is equal to the number of probes made in an unsuccessful search for  $k$  at the time that  $k$  is inserted.

Let  $k$  be the  $i + 1$ -st element. The expected time for a search for  $k$  is at most  $\frac{1}{1-i/n} = \frac{n}{n-i}$ .

$$\begin{aligned} \frac{1}{m} \sum_{i=0}^{m-1} \frac{n}{n-i} &= \frac{n}{m} \sum_{i=0}^{m-1} \frac{1}{n-i} = \frac{1}{\alpha} \sum_{k=n-m+1}^n \frac{1}{k} \\ &\leq \frac{1}{\alpha} \int_{n-m}^n \frac{1}{x} dx = \frac{1}{\alpha} \ln \frac{n}{n-m} = \frac{1}{\alpha} \ln \frac{1}{1-\alpha} . \end{aligned}$$



## 7.7 Hashing

### How do we delete in a hash-table?

- ▶ For hashing with chaining this is not a problem. Simply search for the key, and delete the item in the corresponding list.
- ▶ For open addressing this is difficult.

## 7.7 Hashing

Regardless, of the choice of hash-function there is always an input (a set of keys) that has a very poor worst-case behaviour.

Therefore, so far we assumed that the hash-function is random so that regardless of the input the average case behaviour is good.

However, the assumption of uniform hashing that  $h$  is chosen randomly from all functions  $f : U \rightarrow [0, \dots, n - 1]$  is clearly unrealistic as there are  $n^{|U|}$  such functions. Even writing down such a function would take  $|U| \log n$  bits.

Universal hashing tries to define a set  $\mathcal{H}$  of functions that is much smaller but still leads to good average case behaviour when selecting a hash-function uniformly at random from  $\mathcal{H}$ .

## 7.7 Hashing

### Definition 25

A class  $\mathcal{H}$  of hash-functions from the universe  $U$  into the set  $\{0, \dots, n - 1\}$  is called **universal** if for all  $u_1, u_2 \in U$  with  $u_1 \neq u_2$

$$\Pr[h(u_1) = h(u_2)] \leq \frac{1}{n},$$

where the probability is w. r. t. the choice of a random hash-function from set  $\mathcal{H}$ .

Note that this means that  $\Pr[h(u_1) = h(u_2)] = \frac{1}{n}$ .

## 7.7 Hashing

### Definition 26

A class  $\mathcal{H}$  of hash-functions from the universe  $U$  into the set  $\{0, \dots, n - 1\}$  is called **2-independent** (pairwise independent) if the following two conditions hold

- ▶ For any key  $u \in U$ , and  $t \in \{0, \dots, n - 1\}$   $\Pr[h(u) = t] = \frac{1}{n}$ , i.e., a key is distributed uniformly within the hash-table.
- ▶ For all  $u_1, u_2 \in U$  with  $u_1 \neq u_2$ , and for any two hash-positions  $t_1, t_2$ :

$$\Pr[h(u_1) = t_1 \wedge h(u_2) = t_2] \leq \frac{1}{n^2}.$$

Note that the probability is w. r. t. the choice of a random hash-function from set  $\mathcal{H}$ .

This requirement clearly implies a universal hash-function.

## 7.7 Hashing

### Definition 27

A class  $\mathcal{H}$  of hash-functions from the universe  $U$  into the set  $\{0, \dots, n - 1\}$  is called  **$k$ -independent** if for any choice of  $\ell \leq k$  distinct keys  $u_1, \dots, u_\ell \in U$ , and for any set of  $\ell$  not necessarily distinct hash-positions  $t_1, \dots, t_\ell$ :

$$\Pr[h(u_1) = t_1 \wedge \dots \wedge h(u_\ell) = t_\ell] \leq \frac{1}{n^\ell},$$

where the probability is w. r. t. the choice of a random hash-function from set  $\mathcal{H}$ .

## 7.7 Hashing

### Definition 28

A class  $\mathcal{H}$  of hash-functions from the universe  $U$  into the set  $\{0, \dots, n-1\}$  is called  $(\mu, k)$ -independent if for any choice of  $\ell \leq k$  distinct keys  $u_1, \dots, u_\ell \in U$ , and for any set of  $\ell$  not necessarily distinct hash-positions  $t_1, \dots, t_\ell$ :

$$\Pr[h(u_1) = t_1 \wedge \dots \wedge h(u_\ell) = t_\ell] \leq \left(\frac{\mu}{n}\right)^\ell,$$

where the probability is w. r. t. the choice of a random hash-function from set  $\mathcal{H}$ .

## 7.7 Hashing

Let  $U := \{0, \dots, p-1\}$  for a prime  $p$ . Let  $\mathbb{Z}_p := \{0, \dots, p-1\}$ , and let  $\mathbb{Z}_p^* := \{1, \dots, p-1\}$  denote the set of invertible elements in  $\mathbb{Z}_p$ .

Define

$$h_{a,b}(x) := (ax + b \bmod p) \bmod n$$

### Lemma 29

The class

$$\mathcal{H} = \{h_{a,b} \mid a \in \mathbb{Z}_p^*, b \in \mathbb{Z}_p\}$$

is a universal class of hash-functions from  $U$  to  $\{0, \dots, n-1\}$ .

## 7.7 Hashing

### Proof.

Let  $x, y \in U$  be two distinct keys. We have to show that the probability of a collision is only  $1/n$ .

►  $ax + b \not\equiv ay + b \pmod{p}$

If  $x \neq y$  then  $(x - y) \not\equiv 0 \pmod{p}$ .

Multiplying with  $a \not\equiv 0 \pmod{p}$  gives

$$a(x - y) \not\equiv 0 \pmod{p}$$

where we use that  $\mathbb{Z}_p$  is a field (Körper) and, hence, has no zero divisors (nullteilerfrei).

- The hash-function does not generate collisions before the  $(\bmod n)$ -operation. Furthermore, every choice  $(a, b)$  is mapped to different hash-values  $t_x := h_{a,b}(x)$  and  $t_y := h_{a,b}(y)$ .

This holds because we can compute  $a$  and  $b$  when given  $t_x$  and  $t_y$ :

$$t_x \equiv ax + b \pmod{p}$$

$$t_y \equiv ay + b \pmod{p}$$

$$t_x - t_y \equiv a(x - y) \pmod{p}$$

$$t_y \equiv ay + b \pmod{p}$$

$$a \equiv (t_x - t_y)(x - y)^{-1} \pmod{p}$$

$$b \equiv ay - t_y \pmod{p}$$

## 7.7 Hashing

There is a one-to-one correspondence between hash-functions (pairs  $(a, b)$ ,  $a \neq 0$ ) and pairs  $(t_x, t_y)$ ,  $t_x \neq t_y$ .

Therefore, we can view the first step (before the  $(\text{mod } n)$ -operation) as choosing a pair  $(t_x, t_y)$ ,  $t_x \neq t_y$  uniformly at random.

What happens when we do the  $(\text{mod } n)$  operation?

Fix a value  $t_x$ . There are  $p - 1$  possible values for choosing  $t_y$ .

From the range  $0, \dots, p - 1$  the values  $t_x, t_x + n, t_x + 2n, \dots$  map to  $t_x$  after the modulo-operation. These are at most  $\lceil p/n \rceil$  values.

## 7.7 Hashing

As  $t_y \neq t_x$  there are

$$\left\lceil \frac{p}{n} \right\rceil - 1 \leq \frac{p}{n} + \frac{n-1}{n} - 1 \leq \frac{p-1}{n}$$

possibilities for choosing  $t_y$  such that the final hash-value creates a collision.

This happens with probability at most  $\frac{1}{n}$ .

## 7.7 Hashing

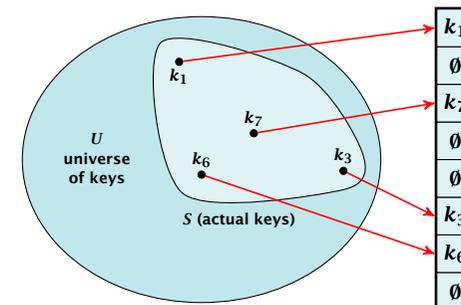
It is also possible to show that  $\mathcal{H}$  is an (almost) pairwise independent class of hash-functions.

$$\frac{\left\lceil \frac{p}{n} \right\rceil^2}{p(p-1)} \leq \Pr_{t_x \neq t_y \in \mathbb{Z}_p^2} \left[ \begin{array}{c} t_x \bmod n = h_1 \\ \wedge \\ t_y \bmod n = h_2 \end{array} \right] \leq \frac{\left\lceil \frac{p}{n} \right\rceil^2}{p(p-1)}$$

Note that the middle is the probability that  $h(x) = h_1$  and  $h(y) = h_2$ . The total number of choices for  $(t_x, t_y)$  is  $p(p-1)$ . The number of choices for  $t_x$  ( $t_y$ ) such that  $t_x \bmod n = h_1$  ( $t_y \bmod n = h_2$ ) lies between  $\lfloor \frac{p}{n} \rfloor$  and  $\lceil \frac{p}{n} \rceil$ .

## Perfect Hashing

Suppose that we **know** the set  $S$  of actual keys (no insert/no delete). Then we may want to design a **simple** hash-function that maps all these keys to different memory locations.



## Perfect Hashing

Let  $m = |S|$ . We could simply choose the hash-table size very large so that we don't get any collisions.

Using a universal hash-function the expected number of collisions is

$$E[\#\text{Collisions}] = \binom{m}{2} \cdot \frac{1}{n}.$$

If we choose  $n = m^2$  the **expected number** of collisions is strictly less than  $\frac{1}{2}$ .

Can we get an upper bound on the **probability of having collisions**?

The probability of having 1 or more collisions can be at most  $\frac{1}{2}$  as otherwise the expectation would be larger than  $\frac{1}{2}$ .

## Perfect Hashing

We can find such a hash-function by a few trials.

However, a hash-table size of  $n = m^2$  is very very high.

We construct a two-level scheme. We first use a hash-function that maps elements from  $S$  to  $m$  buckets.

Let  $m_j$  denote the number of items that are hashed to the  $j$ -th bucket. For each bucket we choose a second hash-function that maps the elements of the bucket into a table of size  $m_j^2$ . The second function can be chosen such that all elements are mapped to different locations.

## Perfect Hashing

The total memory that is required by all hash-tables is  $\sum_j m_j^2$ .

$$\begin{aligned} E\left[\sum_j m_j^2\right] &= E\left[2 \sum_j \binom{m_j}{2} + \sum_j m_j\right] \\ &= 2 E\left[\sum_j \binom{m_j}{2}\right] + E\left[\sum_j m_j\right] \end{aligned}$$

The first expectation is simply the expected number of collisions, for the first level.

$$= 2 \binom{m}{2} \frac{1}{m} + m = 2m - 1$$

## Perfect Hashing

We need only  $\mathcal{O}(m)$  time to construct a hash-function  $h$  with  $\sum_j m_j^2 = \mathcal{O}(4m)$ .

Then we construct a hash-table  $h_j$  for every bucket. This takes expected time  $\mathcal{O}(m_j)$  for every bucket.

We only need that the hash-function is universal!!!!

## Cuckoo Hashing

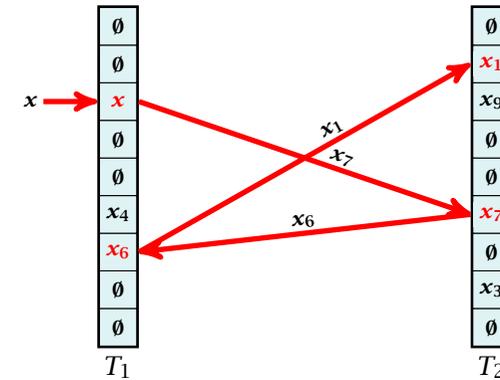
### Goal:

Try to generate a perfect hash-table (constant worst-case search time) in a dynamic scenario.

- ▶ Two hash-tables  $T_1[0, \dots, n - 1]$  and  $T_2[0, \dots, n - 1]$ , with hash-functions  $h_1$ , and  $h_2$ .
- ▶ An object  $x$  is either stored at location  $T_1[h_1(x)]$  or  $T_2[h_2(x)]$ .
- ▶ A search clearly takes constant time if the above constraint is met.

## Cuckoo Hashing

### Insert:



## Cuckoo Hashing

### Algorithm 16 Cuckoo-Insert( $x$ )

- 1: if  $T_1[h_1(x)] = x \vee T_2[h_2(x)] = x$  then return
- 2: steps  $\leftarrow 1$
- 3: while steps  $\leq$  maxsteps do
- 4:     exchange  $x$  and  $T_1[h_1(x)]$
- 5:     if  $x = \text{null}$  then return
- 6:     exchange  $x$  and  $T_2[h_2(x)]$
- 7:     if  $x = \text{null}$  then return
- 8: rehash() // change table-size and rehash everything
- 9: Cuckoo-Insert( $x$ )

## Cuckoo Hashing

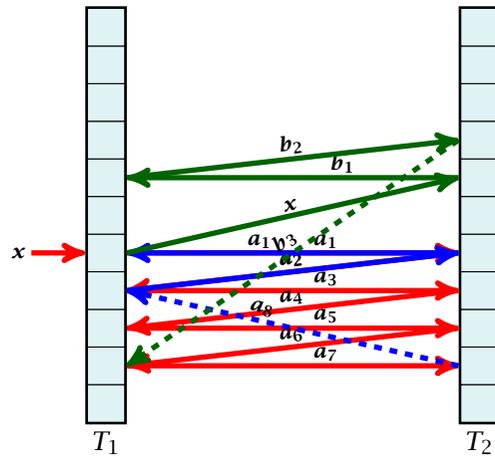
### What is the expected time for an insert-operation?

We first analyze the probability that we end-up in an infinite loop (that is then terminated after maxsteps steps).

Formally what is the probability to enter an infinite loop that touches  $\ell$  different keys (apart from  $x$ )?

## Cuckoo Hashing

Insert:



## Cuckoo Hashing

A cycle-structure is defined by

- ▶  $\ell_a$  keys  $a_1, a_2, \dots, a_{\ell_a}$ ,  $\ell_a \geq 2$ ,
- ▶ An index  $j_a \in \{1, \dots, \ell_a - 1\}$  that defines how much the last item  $a_{\ell_a}$  “jumps back” in the sequence.
- ▶  $\ell_b$  keys  $b_1, b_2, \dots, b_{\ell_b}$ ,  $\ell_b \geq 0$ .
- ▶ An index  $j_b \in \{1, \dots, \ell_a + \ell_b\}$  that defines how much the last item  $b_{\ell_b}$  “jumps back” in the sequence.
- ▶ An assignment of positions for the keys in both tables. Formally we have positions  $p_1, \dots, p_{\ell_a}$ , and  $p'_1, \dots, p'_{\ell_b}$ .
- ▶ The size of a cycle-structure is defined as  $\ell_a + \ell_b$ .

## Cuckoo Hashing

We say a cycle-structure is **active** for key  $x$  if the hash-functions are chosen in such a way that the hash-function results match the pre-defined key-positions.

- ▶  $h_1(x) = h_1(a_1) = p_1$
- ▶  $h_2(a_1) = h_2(a_2) = p_2$
- ▶  $h_1(a_2) = h_1(a_3) = p_3$
- ▶ ...
- ▶ if  $\ell_a$  is even then  $h_1(a_{\ell}) = p_{s_a}$ , otw.  $h_2(a_{\ell}) = p_{s_a}$
- ▶  $h_2(x) = h_2(b_1) = p'_1$
- ▶  $h_1(b_1) = h_1(b_2) = p'_2$
- ▶ ...

## Cuckoo Hashing

**Observation** If we end up in an infinite loop there must exist a cycle-structure that is active for  $x$ .

## Cuckoo Hashing

A cycle-structure is defined **without** knowing the hash-functions.

Whether a cycle-structure is active for key  $x$  depends on the hash-functions.

### Lemma 30

A given cycle-structure of size  $s$  is active for key  $x$  with probability at most

$$\left(\frac{\mu}{n}\right)^{2(s+1)},$$

if we use  $(\mu, s + 1)$ -independent hash-functions.

## Cuckoo Hashing

### Proof.

All positions are fixed by the cycle-structure. Therefore we ask for the probability of mapping  $s + 1$  keys (the  $a$ -keys, the  $b$ -keys and  $x$ ) to pre-specified positions in  $T_1$ , **and** to pre-specified positions in  $T_2$ .

The probability is

$$\left(\frac{\mu}{n}\right)^{s+1} \cdot \left(\frac{\mu}{n}\right)^{s+1},$$

since  $h_1$  and  $h_2$  are chosen independently.  $\square$

## Cuckoo Hashing

**The number of cycle-structures of size  $s$  is small:**

- ▶ There are at most  $s$  ways to choose  $\ell_a$ . This fixes  $\ell_b$ .
- ▶ There are at most  $s^2$  ways to choose  $j_a$ , and  $j_b$ .
- ▶ There are at most  $m^s$  possibilities to choose the keys  $a_1, \dots, a_{\ell_a}$  and  $b_1, \dots, b_{\ell_b}$ .
- ▶ There are at most  $n^s$  choices for choosing the positions  $p_1, \dots, p_{\ell_a}$  and  $p'_1, \dots, p'_{\ell_a}$ .

## Cuckoo Hashing

Hence, there are at most  $s^3(mn)^2$  cycle-structures of size  $s$ .

The probability that there is an active cycle-structure of size  $s$  is at most

$$\begin{aligned} s^3(mn)^s \cdot \left(\frac{\mu}{n}\right)^{2(s+1)} &= \frac{s^3}{mn} (mn)^{s+1} \left(\frac{\mu^2}{n^2}\right)^{s+1} \\ &= \frac{s^3}{mn} \left(\frac{\mu^2 m}{n}\right)^{s+1} \end{aligned}$$

## Cuckoo Hashing

If we make sure that  $n \geq (1 + \delta)\mu^2 m$  for a constant  $\delta$  (i.e., the hash-table is not too full) we obtain

Pr[there exists an active cycle-structure]

$$\begin{aligned} &\leq \sum_{s=2}^{\infty} \text{Pr}[\text{there exists an act. cycle-structure of size } s] \\ &\leq \sum_{s=2}^{\infty} \frac{s^3}{mn} \left(\frac{\mu^2 m}{n}\right)^{s+1} \\ &\leq \frac{1}{mn} \sum_{s=0}^{\infty} s^3 \left(\frac{1}{1+\delta}\right)^s \\ &\leq \frac{1}{m^2} \cdot \mathcal{O}(1) . \end{aligned}$$

Now assume that the insert operation takes  $t$  steps and does not create an infinite loop.

Consider the sequences  $x, a_1, a_2, \dots, a_{\ell_a}$  and  $x, b_1, b_2, \dots, b_{\ell_b}$  where the  $a_i$ 's and  $b_i$ 's are defined as before (but for the construction we only use keys examined during the while loop)

If the insert operation takes  $t$  steps then

$$t \leq 2\ell_a + 2\ell_b + 2$$

as no key is examined more than twice.

Hence, one of the sequences  $x, a_1, a_2, \dots, a_{\ell_a}$  and  $x, b_1, b_2, \dots, b_{\ell_b}$  must contain at least  $t/4$  keys (either  $\ell_a + 1$  or  $\ell_b + 1$  must be larger than  $t/4$ ).

Define a sub-sequence of length  $\ell$  starting with  $x$ , as a sequence  $x_1, \dots, x_\ell$  of keys with  $x_1 = x$ , together with  $\ell + 1$  positions  $p_0, p_1, \dots, p_\ell$  from  $\{0, \dots, n - 1\}$ .

We say a sub-sequence is **right-active** for  $h_1$  and  $h_2$  if

$$\begin{aligned} h_1(x) = h_1(x_1) = p_0, h_2(x_1) = h_2(x_2) = p_1, \\ h_1(x_2) = h_1(x_3) = p_2, h_2(x_3) = h_2(x_4) = p_3, \dots \end{aligned}$$

We say a sub-sequence is **left-active** for  $h_1$  and  $h_2$  if  $h_2(x_1) = p_0$ ,

$$\begin{aligned} h_1(x_1) = h_1(x_2) = p_1, h_2(x_2) = h_2(x_3) = p_2, \\ h_1(x_3) = h_1(x_4) = p_3, \dots \end{aligned}$$

For an active sequence starting with  $x$  the key  $x$  is supposed to have a collision with the second element in the sequence. This collision could either be in the table  $T_1$  (left) or in the table  $T_2$  (right). Therefore the above definitions differentiate between left-active and right-active.

## Cuckoo Hashing

### Observation:

If the insert takes  $t \geq 4\ell$  steps there must either be a left-active or a right-active sub-sequence of length  $\ell$  starting with  $x$ .

## Cuckoo Hashing

The probability that a given sub-sequence is left-active (right-active) is at most

$$\left(\frac{\mu}{n}\right)^{2\ell},$$

if we use  $(\mu, \ell)$ -independent hash-functions. This holds since there are  $\ell$  keys whose hash-values (two values per key) have to map to pre-specified positions.

## Cuckoo Hashing

The number of sequences is at most  $m^{\ell-1}p^{\ell+1}$  as we can choose  $\ell - 1$  keys (apart from  $x$ ) and we can choose  $\ell + 1$  positions  $p_0, \dots, p_\ell$ .

The probability that there exists a left-active **or** right-active sequence of length  $\ell$  is at most

Pr[there exists active sequ. of length  $\ell$ ]

$$\begin{aligned} &\leq 2 \cdot m^{\ell-1} \cdot n^{\ell+1} \cdot \left(\frac{\mu}{n}\right)^{2\ell} \\ &\leq 2 \left(\frac{1}{1+\delta}\right)^\ell \end{aligned}$$

## Cuckoo Hashing

If the search does not run into an infinite loop the probability that it takes more than  $4\ell$  steps is at most

$$2 \left(\frac{1}{1+\delta}\right)^\ell$$

We choose  $\text{maxsteps} = 4(1 + 2 \log m) / \log(1 + \delta)$ . Then the probability of terminating the while-loop because of reaching  $\text{maxsteps}$  is only  $\mathcal{O}\left(\frac{1}{m^2}\right)$  ( $\mathcal{O}(1/m^2)$  because of reaching an infinite loop and  $1/m^2$  because the search takes  $\text{maxsteps}$  steps without running into a loop).

## Cuckoo Hashing

The expected time for an insert under the condition that  $\text{maxsteps}$  is not reached is

$$\begin{aligned} &\sum_{\ell \geq 0} \text{Pr}[\text{search takes at least } \ell \text{ steps} \mid \text{iteration successful}] \\ &\leq \sum_{\ell \geq 0} 8 \left(\frac{1}{1+\delta}\right)^\ell = \mathcal{O}(1). \end{aligned}$$

More generally, the above expression gives a bound on the cost in the successful iteration of an insert-operation (there is exactly one successful iteration).

An iteration that is not successful induces cost  $\mathcal{O}(m)$  for doing a complete rehash.

## Cuckoo Hashing

The expected number of unsuccessful operations is  $\mathcal{O}(\frac{1}{m^2})$ .  
Hence, the expected cost in unsuccessful iterations is only  $\mathcal{O}(\frac{1}{m})$ .  
Hence, the total expected cost for an insert-operation is constant.

## Cuckoo Hashing

**What kind of hash-functions do we need?**  
Since maxsteps is  $\Theta(\log m)$  it is sufficient to have  $(\mu, \Theta(\log m))$ -independent hash-functions.

## Cuckoo Hashing

**How do we make sure that  $n \geq \mu^2(1 + \delta)m$ ?**

- ▶ Let  $\alpha := 1/(\mu^2(1 + \delta))$ .
- ▶ Keep track of the number of elements in the table. Whenever  $m \geq \alpha n$  we double  $n$  and do a complete re-hash (table-expand).
- ▶ Whenever  $m$  drops below  $\frac{\alpha}{4}n$  we divide  $n$  by 2 and do a rehash (table-shrink).
- ▶ Note that right after a change in table-size we have  $m = \frac{\alpha}{2}n$ . In order for a table-expand to occur at least  $\frac{\alpha}{2}n$  insertions are required. Similar, for a table-shrink at least  $\frac{\alpha}{4}$  deletions must occur.
- ▶ Therefore we can amortize the rehash cost after a change in table-size against the cost for insertions and deletions.

### Definition 31

Let  $d \in \mathbb{N}$ ;  $q \geq n$  be a prime; and let  $\vec{a} \in \{0, \dots, q-1\}^{d+1}$ . Define for  $x \in \{0, \dots, q\}$

$$h_{\vec{a}}(x) := \left( \sum_{i=0}^d a_i x^i \bmod q \right) \bmod n .$$

Let  $\mathcal{H}_n^d := \{h_{\vec{a}} \mid \vec{a} \in \{0, \dots, q\}^{d+1}\}$ . The class  $\mathcal{H}_n^d$  is  $(2, d+1)$ -independent.

For the coefficients  $\bar{a} \in \{0, \dots, q-1\}^{d+1}$  let  $f_{\bar{a}}$  denote the polynomial

$$f_{\bar{a}}(x) = \left( \sum_{i=0}^d a_i x^i \right) \bmod q$$

The polynomial is defined by  $d+1$  distinct points.

Fix  $\ell \leq d+1$ ; let  $x_1, \dots, x_\ell \in \{0, \dots, q-1\}$  be keys, and let  $t_1, \dots, t_\ell$  denote the corresponding hash-function values.

Let  $A^\ell = \{h_{\bar{a}} \in \mathcal{H} \mid h_{\bar{a}}(x_i) = t_i \text{ for all } i \in \{1, \dots, \ell\}\}$

Then

$$h_{\bar{a}} \in A^\ell \Leftrightarrow h_{\bar{a}} = f_{\bar{a}} \bmod n \text{ and}$$

$$f_{\bar{a}}(x_i) \in \{t_i + \alpha \cdot n \mid \alpha \in \{0, \dots, \lceil \frac{q}{n} \rceil - 1\}\}$$

Therefore I have

$$|B_1| \cdot \dots \cdot |B_\ell| \cdot q^{d-\ell+1} \leq \lceil \frac{q}{n} \rceil^\ell \cdot q^{d-\ell+1}$$

possibilities to choose  $\bar{a}$  such that  $h_{\bar{a}} \in A_\ell$ .

Therefore the probability of choosing  $h_{\bar{a}}$  from  $A_\ell$  is only

$$\frac{\lceil \frac{q}{n} \rceil^\ell \cdot q^{d-\ell+1}}{q^{d+1}} \leq \left( \frac{2}{n} \right)^\ell$$