Course "Polynomials: Their Power and How to Use Them", JASS'07

Differential Polynomials

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Conclusion

Differential Ring

Definition 1 (Differential Ring)

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A differential ring R is a ring with differential operators $\Delta = \{\delta_1, \dots, \delta_m\}$ and for all i, j:

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 Θ denotes the free abelian monoid generated by $\Delta,$ alias $\Delta^*,$ members of Θ are called *derivations*.

Differential Ideal

Definition 2 (Differential Ideal)

An *differential ideal I* is a ideal of *R* with $\forall \delta \in \Delta : \delta I \subset I$. We write:

[S] differential ideal generated by set S

 $\{S\}$ perfect differential ideal generated by set S

Example

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- 1. fx^2 for $f \in F\{x\}$
- 2. $f_{x(1)}x$
- 3. $f(x_{(2)}x + (x_{(1)})^2)$ and therefore $f(x_{(1)})^2x$

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5.
$$f(x_{(k)})^{s}$$
 for some $s > 1$
6. ...

Notation

$F\{X\}$	differential polynomials over field F with variables X
lm(f)	leading monomial of <i>f</i>
lc(f)	leading coefficient of f
lt(f)	= lc(f)lm(f) leading term of f
$\theta x = x_{(\theta)}$	derivation $ heta \in \Theta$ of variable x
$\operatorname{ord}(\delta^{lpha} x)$	$=\sum_{i=1}^{n} \alpha_i$ order of $\delta^{\alpha} x$
$deg(v^eta)$	$=\sum_{i=1}^reta_i$ degree of v^eta , $\delta^lpha\in\Theta$
$wt(v^eta)$	$=\sum_{i=1}^{r}eta_i \operatorname{ord}(v_i)$ weight of v^{eta}

Nonrecursive Ideals

Example 4 Consider over $\mathbb{Z}\{x\}$ with $\Delta = \{d\}$: $f_i = (d^i x)^2$ for $i \ge 0$ and $I_k = [f_0, \dots, f_k]$. Then: $I_0 \subsetneq I_1 \subsetneq \dots$

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Proof.

 deg(f_i) = 2, wt(f_i) = 2i ⇒ d^jf_i is homogeneous of degree 2 and isobaric of weight 2i + j

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- ▶ deg(f_i) = 2, wt(f_i) = 2i ⇒ d^jf_i is homogeneous of degree 2 and isobaric of weight 2i + j
- Assume $f_n = \sum_{i=0}^{n-1} \sum_{j=0}^{k_i} \alpha_{i,j} d^j(f_i)$

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Proof.

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- If deg(α_{i,j}) ≥ 1, these terms must cancel (deg(f_n) = 2, derivatives of f_i are homogeneous).
- \Rightarrow WLOG: $\alpha_{i,j} \in \mathbb{Z}$

• $\alpha_{i,j} = 0$ for $j \neq 2n - 2i$ (wt(f_n) = 2n, $d^j f_i$ are isobaric).

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Nonrecursive Ideals (2)

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$$\Rightarrow f_n = c_0 d^{2n} f_0 + c_1 d^{(2n-2)} f_1 + \ldots + c_{n-1} d^2 f_{n-1} \text{ for } c_i \in \mathbb{Z}$$

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- $d^{2n}f_0$ contains the monomial $x_{(2n)}x \Rightarrow c_0 = 0$
- Analogous reasoning for $d^{2n-2i}f_i$ yields $c_i = 0$
- Contradiction: $f_n \neq 0$

Nonrecursive Ideals (3)

Example 6 Let $S \subset \mathbb{N}_0$ and $I_S = [\{f_i : i \in S\}]$. Then

 $f_i \in I_S \Leftrightarrow i \in S$

So for a nonrecursive set $S \subset \mathbb{N}_0$ there is no algorithm to decide if a given differential polynomial g is in I_S .

Algebraic Aspects	
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Reduction

Admissible Orderings

Definition 7 (Ranking)

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- 1. The restriction of < to ΘX is a ranking.
- 2. $1 \le f$ for all $f \in M$
- 3. $f < g \Rightarrow hf < hg$ for all $f, g, h \in M$

Examples of Rankings

$$X = \{x_1, ..., x_n\}$$
 with $x_1 < ... < x_n$.

Example 9 (Lexicographic Ranking on ΘX)

Consider a monomial ordering < on the differential operators Θ . Then the *lexicographic ranking* is given by $\theta x_i < \eta x_k$ iff i < k or i = k and $\theta < \eta$.

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► For $|X| = |\Delta| = 1$ there is only one ranking: $x_{(i)} < x_{(i+1)}$

Examples of Admissible Orderings

$$f = \prod_{i=1}^{r} v_i^{\alpha_i} \text{ with } v_1 > \ldots > v_r.$$

$$g = \prod_{i=1}^{s} w_i^{\beta_i} \text{ with } w_1 > \ldots > w_s.$$

Example 11 (Lexicographic Ordering on M)

Given an ranking on ΘX .

 $f <_{lex} g$ iff $\exists k \leq r, s : v_i = w_i$ for i < k and $v_k < w_k$ or $v_k = w_k$ and $\alpha_i < \beta_i$ or $v_i = w_i$ for $i \leq r$ and r < s.

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Example 12 (Graded (by Degree) Reverse Lexicographic Ordering on M)

Given an ranking on ΘX .

 $f <_{degrevlex} g$ iff $\deg(f) < \deg(g)$ or $\deg(f) = \deg(g)$ and $f <_{revlex} g$.

Reduction

Definition 13 f is reduced by g to h iff $\exists \theta \in \Theta, m \in M$ such that $\operatorname{Im}(f) = \operatorname{Im}(m\theta g)$ and $h = f - \frac{\operatorname{lc}(f)}{\operatorname{Ic}(g)}m\theta g$. f is reducable by g, iff there is an h such that f is reduced by g to h.

Reduction Algorithm

Monoideals and Standard Bases

Definition 14 (Monoideal)

 $E \subset M$ is called a *monoideal* iff $ME \subset E$ and $Im(\Delta E) \subset E$.

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Definition 15 (Standard Basis)

 $G \subset I$ is called a *standard basis* iff Im(G) generates Im(I) as monoideal.

Example 16 (Monoideal - Lexicographic Ordering) Members of the monoideal *I* generated by x^2 over $F\{x\}$ with $\Delta = \{d\}$ using lexicographic ordering $(x_{(k)} := d^k x)$:

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- 4. $mx_{(k)}x$

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- 2. $mx_{(1)}x$
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- 5. BUT $(x_{(k)})^r \notin I$

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- 6. $mx_{(k)}x_{(k+1)}$
- 7. $mx_{(k)}^2$

Membership Problem

Theorem 18 Let G be a set of polynomials, I a differential ideal. Then the following propositions are equivalent:

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Proof:

⇒ Let $0 \neq f \in I$. Then f is reducible by G and the reduction $h \in I$, Im(h) < Im(f).

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- 2. For $f \in F\{X\}$ yields: $f \in I \Leftrightarrow f$ is reduced to 0 by G.

- ⇒ Let $0 \neq f \in I$. Then f is reducible by G and the reduction $h \in I$, Im(h) < Im(f).
- $\Leftarrow g \in G \Rightarrow g \text{ is reduced to 0 by } G \Rightarrow G \subset I$ $f \in I \Rightarrow f \text{ is reduced to 0 by } G \Rightarrow \operatorname{Im} I \subset \operatorname{Im}(M \ominus G)$

Infinite Standard Bases

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Remember $I = [x^2]$ over $F\{x\}$ with $\Delta = \{d\}$. Then for every $r \ge 0$ there is an q > 1 such that $(x_{(r)})^q \in I$.

► LEX: $\operatorname{Im}(d(\prod_{i=1}^{r} v_{i}^{\alpha_{i}})) = d(v_{1})v_{1}^{\alpha_{1}-1}\prod_{i=2}^{r} v_{i}^{\alpha_{i}}$ if $v_{1} > \ldots > v_{r}$. Therefore $(x_{(r)})^{s}$ for every $r \ge 0$ for some s > 0 is in every standard basis (\rightarrow infinite).

Infinite Standard Bases

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- $r \geq 0$ there is an q > 1 such that $(x_{(r)})^q \in I$.
 - ► LEX: $\operatorname{Im}(d(\prod_{i=1}^{r} v_{i}^{\alpha_{i}})) = d(v_{1})v_{1}^{\alpha_{1}-1}\prod_{i=2}^{r} v_{i}^{\alpha_{i}}$ if $v_{1} > \ldots > v_{r}$. Therefore $(x_{(r)})^{s}$ for every $r \ge 0$ for some s > 0 is in every standard basis (\rightarrow infinite).
 - DEGREVLEX: x^2 is a standard basis.

Algebraic Aspects
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Reduction

Infinite Standard Bases (2)

Example 20

Conjecture: There is no finite standard basis for $[x_{(1)}x]$ for no monomial ordering.
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2. $x_{(r)}^{t_{r}}$ for $r \ge 1$ and some $t_{r} \ge r + 2$
3. $x_{(r)}^{2}x_{(r+2)}^{2}\cdots x_{(r+2k_{r})}^{2}$ for $r \ge 0$ and some k_{r}

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4. $x_{(r)}^{2}x_{(r+3)}^{2}\cdots x_{(r+3l_{r})}^{2}$ for $r \ge 0$ and some $l_{r} \ge 2r - 1$
belong to the ideal $[x_{(1)}x]$.

Manifolds

We choose e.g. F as set of all meromorphic functions.

Definition 22

Let Σ be a system of differential polynomials over $F\{x_1, \ldots, x_n\}$, F_1 an extension of F.

If $Y = (y_1, \ldots, y_n) \in F_1^n$ such that for all $f \in \Sigma$ $f(y_1, \ldots, y_n) = 0$, then Y is a zero of Σ . The set of all zeros of Σ (for all possible extentions of F) is called *manifold*.

Unions of Manifolds

▶ Let M_1, M_2 be the manifolds of Σ_1, Σ_2 . If $M_1 \cap M_2 \neq \emptyset$ then $M_1 \cap M_2$ is the manifold of $\Sigma_1 + \Sigma_2$. $M_1 \cup M_2$ is the manifold of $\{AB : A \in \Sigma_1, B \in \Sigma_2\}$.

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- M is called *reducible* if it is union of two manifolds M₁, M₂ ≠ M.
- Otherwise it is called *irreducible*.

Irreducible Manifolds

Lemma 23 M is irreducible \Leftrightarrow (AB vanishes over $M \Rightarrow A$ or B vanishes over M)

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- $\leftarrow \text{ Let } M \text{ be proper union of } M_1, M_2 \text{ with systems } \Sigma_1, \Sigma_2. \text{ Then } \\ \exists A_i \in \Sigma_i \text{ be differential polynomials that do not vanish over } \\ M. A_1A_2 \text{ vanishes over } M. \end{cases}$

Irreducible Manifolds

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I.e. irreducible manifolds correspond to prime ideals.

Decomposition

Theorem 24

Every manifold is the union of a finite number of irreducible manifolds.

Decomposition (2)

Consider differential polynomials over $F\{x\}$ with $\Delta = \{d\}$ and F the meromorphic functions:

Example 25 Let $\Sigma = [f]$ with $f = x_{(1)}^2 - 4x$. Then $df = 2x_{(1)}(x_{(2)} - 2)$.

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- ► x₍₁₎ = 0 has the solution x(t) = c. Looking at f, only c = 0 is valid.
- ► $x_{(2)} 2 = 0$ has the solution $x(t) = (t+b)^2 + c$. Again c = 0.
- There are no other solutions.

The Theorem of Zeros

Theorem 26 Let $\Sigma = [f_1, ..., f_k]$ with manifold M. If g vanishes over M then $g^s \in \Sigma$ for some $s \in \mathbb{N}_0$.

The Theorem of Zeros

Theorem 26 Let $\Sigma = [f_1, \ldots, f_k]$ with manifold M. If g vanishes over M then $g^s \in \Sigma$ for some $s \in \mathbb{N}_0$.

► So the manifolds are represented by perfect ideals.

The Ritt-Braudenbush Theorem

Theorem 27 Every perfect differential ideal has a finite basis.

Membership Test for Perfect Differential Ideals/Manifolds

Let Σ be a finite system of differential polynomials. Question: Is $f \in {\Sigma}$?

 Resolve Σ into prime ideals (resp. the corresponding manifold into irreducible manifolds).

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Let Σ be a finite system of differential polynomials. Question: Is $f \in {\Sigma}$?

- Resolve Σ into prime ideals (resp. the corresponding manifold into irreducible manifolds).
- *f* must be member of each of these prime ideals.
- Test if the remainder of f with respect to the characteristic sets of the prime ideals is zero.

 Differential polynomials can be used to model differential equation systems.

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- Manifolds (solutions) correspond to perfect ideals, that are easier to handle.
- ► For some important problems (finite) algorithms exist.

Thank you for the attention

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