Course "Polynomials: Their Power and How to Use Them", JASS'07

Basics about Polynomials

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Abstract

After introducing polynomials, my talk will concentrate on algorithms for polynomial division or pseudodivision, on methods to find the gcd of polynomials or to construct pseudo-remainder-series. In the second half of the talk we will use this knowledge to develop an algorithm to count and isolate real roots of polynomials.

1 Basic definitions

1.1 Algebraic structures

Definition 1. A ring is an algebraic system $(R, +, \cdot)$ satisfying the following:

- The set R with the addition + is an abelian group.
- The multiplication \cdot is associative.
- Multiplication distributes over addition:

 $a \cdot (b+c) = a \cdot b + a \cdot c$ and $(b+c) \cdot a = b \cdot a + c \cdot a$

for all $a, b, c \in R$.

We say that $(R, +, \cdot)$ is a ring with unity, if R contains an multiplicative identity, denoted by 1. For commutative rings, multiplication has to be commutative, too.

For a commutative ring $(R, +, \cdot)$ with unity we define for the elements of R:

- $a \in R$ divides $c \in R$, if there exists $b \in R$, so that $c = a \cdot b$.
- In particular, $a \in R$, $a \neq 0$ is called a zerodivisor, if there exists $b \in R$, $b \neq 0$ with $a \cdot b = 0$.
- $u \in R$ is called a unit if there is an multiplicative inverse $v \in R$ so that $u \cdot v = 1$.

Example 2. The residue classes $\mathbb{Z}/8\mathbb{Z}$ with the usual addition and multiplication form a ring. The equivalence classes of odd numbers are units, the equivalence classes [2], [4] and [6] are zerodivisors.

Definition 3. A nontrivial ring (a ring that contains more than one element), with unity and without zero divisors is called domain. If multiplication is commutative, we call it integral domain.

Example 4. The ring of integers $(\mathbb{Z}, +, \cdot)$ is an integral domain with units 1 and -1.

Definition 5. A field is a commutative, nontrivial ring with unity, in which every nonzero element is a unit.

Well known examples for fields are the rationals \mathbb{Q} , the reals \mathbb{R} or the complex numbers \mathbb{C} .

1.2 Polynomials

Definition 6. Let $(R, +, \cdot)$ be a ring and S be the set of sequences

 $\{a_0, a_1, \ldots\}$ with $a_i \in R$ for all $i \in \mathbb{N}_0$

such that $a_i = 0$ for all but a finite number of $i \in \mathbb{N}_0$. If we define addition and multiplication on S by:

$$\{a_0, a_1, \ldots\} + \{b_0, b_1, \ldots\} := \{a_0 + b_0, a_1 + b_1, \ldots\}$$
$$\{a_0, a_1, \ldots\} \cdot \{b_0, b_1, \ldots\} := \{a_0 \cdot b_0, a_1 \cdot b_0 + a_0 \cdot b_1, \ldots\}$$

then $(S, +, \cdot)$ is the ring R[X] of univariate polynomials over R.

Definition 7. For a polynomial $P = \{a_0, a_1, ...\} \in R[X]$, the degree deg(P) is defined as the maximal number n so, that $a_n \neq 0$. In this case, $lc(P) := a_n$ is called the leading coefficient of P.

By definition of addition and multiplication on R[X] we have for two polynomials P, Q:

- $deg(P+Q) \le max\{deg(P), deg(Q)\}$
- $deg(P \cdot Q) \le deg(P) + deg(Q)$
- if R contains no zerodivisors, its even $deg(P \cdot Q) = deg(P) + deg(Q)$.

For a ring with unity, we can define the variable

$$X := \{0, 1, 0, 0, ...\}$$

With this definition we have

$$X^n := \{\underbrace{0, ..., 0}_{n \text{ zeroes}}, 1, 0, 0, ...\}$$

Now we can write a polynomial of degree n like this:

$$\{a_0, a_1, \ldots\} = \sum_{k=0}^n a_k X^k$$

For any polynomial $P(X) = \sum_{k=0}^{n} a_k X^k$ in R[X] we can define a function

$$P: R \to R$$
, with $P(z) := \sum_{k=0}^{n} a_k z^k$

by substituting the formal symbol X by elements of R. Note that, for different polynomials P(X) and Q(X), the functions P and Q can be equal.

Example 8. For p prime, $z^p - z = 0$ for all elements of $\mathbb{Z}/p\mathbb{Z}$, but $X^p - X$ is obviously *not* the zero polynomial (the polynomial with zero coefficients).

The definition of multivariate polynomials follows from the univariate case:

Definition 9. Let R be a ring. For $m \in \mathbb{N}$ we define the ring of multivariate polynomials in m variables $\{X_1, ..., X_m\}$ over R by

$$R[X_1, ..., X_m] = R[X_1, ..., X_{m-1}][X_m]$$

2 First properties and algorithms

2.1 Polynomial representations

To store and to represent a polynomial P(X) of degree n, we can use a dense representation like

$$P = \{X, n, a_n, ..., a_1, a_0\}$$

where we mention all coefficients of P. However, for a polynomial with many zero coefficients it is enough to store the nonzero coefficients in a sparse representation:

$$P = \{X, a_s, m_s, \dots, a_2, m_2, a_1, m_1\},\$$

where a_i are the nonzero coefficients and m_i are the exponents in decreasing order.

2.2 Polynomial operations

Now, we want to take a look on the computational complexity of addition and multiplication in R[X]. Assume that operations in R can be done in time O(1), and let P(X) and Q(X) two Polynomials, with deg(P) = m, deg(Q) = n, and let s and t be the numbers of nonzero coefficients. It is obvious that the calculation of P+Q is done in a time of $O(max\{m,n\})$ in dense representation, while sparse representation leads to a computing time of $O(max\{s,t\})$.

Theorem 10. In dense representation, the calculation of $P \cdot Q$ is done in O(mn), while in sparse representation the calculation is done in $O(st \cdot log_2(t))$

Proof. (dense case)

$$P(X) \cdot Q(X) = \left(\sum_{j=0}^{m} a_j X^j\right) \cdot \left(\sum_{k=0}^{n} b_k X^k\right) = \sum_{l=0}^{m+n} c_l X^l$$

with $c_l = \sum_{s=0}^{l} a_s b_{l-s}$. Thus, we are doing $(m+1) \cdot (n+1)$ multiplications and mn additions.

The sparse algorithm is illustrated by an (not very sparse) example: For s = 3, t = 4, we want to multiply $X^3 + 7X + 9$ and $X^4 + X^2 + 3X + 2$ over the integers. First, we calculate all $s \cdot t$ monomials:

$$\begin{array}{ccccc} X^7 & 7X^5 & 9X^4 \\ X^5 & 7X^3 & 9X^2 \\ 3X^4 & 21X^2 & 27X \\ 2X^3 & 14X & 18 \end{array}$$

Then we fuse, sort, and where possible, add, neighbouring rows:

Sorting again, we have:

$$X^7 \quad 8X^5 \quad 12X^4 \quad 9X^3 \quad 30X^2 \quad 41X \quad 18$$

2.3 Polynomial division

Theorem 11. Let R be an integral domain and $P_1(X)$ and $P_2(X)$ two polynomials over R with $lc(P_2)$ a unit in R. Then there exist unique Q(X), R(X), so that:

$$P_1(X) = Q(X) \cdot P_2(X) + R(X)$$
 and $deg(R(X)) < deg(P_2(X))$.

Proof. Existence: For $deg(P_2(X)) > deg(P_1(X))$, choose $R(X) = P_1(X)$, Q(X) = 0. For $n = deg(P_2(X)) \le m = deg(P_1(X))$, defining

$$P_1'(X) := P_1(X) - lc(P_2)^{-1}lc(P_1) \cdot X^{m-n} \cdot P_2(X)$$

we can successively cancel off the leading terms of $P_1(X)$, until we are in the first case. Thats also the idea for the next algorithm.

Uniqueness: Let $\bar{Q}(X), \bar{R}(X)$ be another solution. Then

$$(\bar{Q}(X) - Q(X))P_2(X) = R(X) - \bar{R}(X)$$
 and $deg(R(X) - \bar{R}(X)) < deg(P_2(X))$.

Since R is an integral domain, this is only possible for $Q(X) = \overline{Q}(X)$ and $R(X) = \overline{R}(X)$.

Definition 12. In this situation, we call $Q(X) =: quo(P_1(X), P_2(X))$ the quotient and $R(X) =: rem(P_1(X), P_2(X))$ the remainder of $P_1(X), P_2(X)$.

Let $P_1(X) = \sum_{j=0}^m a_j X^j$, $P_2(X) = \sum_{k=0}^n b_k X^k$, $m \ge n \ge 0$, and b_n be a unit. The algorithm for polynomial division is:

$$\begin{array}{l} \underline{\text{for } i = m - n \ \underline{\text{down to}} \ 0 \ \underline{\text{do}}} \\ q_i := a_{n+i} b_n^{-1} \\ \underline{\text{for } l = n + i - 1 \ \underline{\text{down to}} \ i \ \underline{\text{do}}} \\ a_l := a_l - q_i b_{l-i} \\ \underline{\text{od}} \\ \underline{\text{od}} \end{array}$$

Then, $Q(X) = \sum_{i=0}^{m-n} q_i X^i$, and $R(X) = \sum_{l=0}^{n-1} a_l X^l$. Computing time: Assuming that operations in R take O(1), the whole algorithm is done in O(n(m-n+1)). Let R be an integral domain.

Definition 13. For $P(X) \in R[X]$, $\alpha \in R$ is called a root of P(X), if $P(\alpha)=0$.

Theorem 14. $\alpha \in R$ is a root of P(X) if $(X - \alpha)$ divides P(X).

Proof. Observe that $rem(P(X), (X - \alpha)) = P(\alpha)$.

Definition 15. $\alpha \in R$ is a root with multiplicity m, if $(X - \alpha)^m$ divides P(X).

Theorem 16. If $P(X) \neq 0$, P(X) can have at most deg(P(X)) roots, counting multiplicities.

2.4 Field extensions

Definition 17. Let K be a field, and $M(X) \in K[X]$ with deg(M(X)) > 0. Then we can define the equivalence relation $\equiv_{M(X)}$ on K[X]:

$$P(X) \equiv_{M(X)} Q(X)$$
 if $rem(P(X), M(X)) = rem(Q(X), M(X))$.

The set of equivalence classes, denoted by $K[X]_{M(X)}$, together with the operations

$$[P(X)]_{M(X)} + [Q(X)]_{M(X)} := [P(X) + Q(X)]_{M(X)}$$
$$[P(X)]_{M(X)} \cdot [Q(X)]_{M(X)} := [P(X) \cdot Q(X)]_{M(X)}$$

is a commutative ring with unity.

Definition 18. A polynomial $P(X) \in R[X]$, R an integral domain, is called irreducible, if, whenever $P(X) = P_1(X) \cdot P_2(X)$, $P_1(X)$ or $P_2(X)$ is a unit of R[X].

Example 19. $2X^2 + 4$ is reducible both over \mathbb{Z} and \mathbb{C} , but not over \mathbb{R} .

Theorem 20. For K a field and $M(X) \in K[X]$ with deg(M(X)) > 0, $K[X]_{M(X)}$ is a field if and only if M(X) is irreducible over K.

Proof. "⇒": If M(X) was reducible, $K[X]_{M(X)}$ would contain zerodivisors. "⇐": We proof that every nonzero element of $K[X]_{M(X)}$ is a unit. Let $[P(X)]_{M(X)} \neq [0]_{M(X)}$. As we will see later, there are $G(X), H(X) \in K[X]$ with $P(X) \cdot G(X) + M(X) \cdot H(X) = 1$, and therefore $[P(X)]_{M(X)} \cdot [G(X)]_{M(X)} = [1]_{M(X)}$.

In this case, $K[X]_{M(X)}$ contains a subfield isomorphic to K and is therefore a field extension of K.

Example 21. Let $K = \mathbb{R}$ and $M(X) = X^2 + 1$. Then all elements of $\mathbb{R}[X]_{X^2+1}$ are of the form $a \cdot [1] + b \cdot [X]$ with $a, b \in \mathbb{R}$. Addition and multiplication are given by:

$$\begin{aligned} (a[1] + b[X]) + (c[1] + d[X]) &= (a + c)[1] + (b + d)[X] \\ (a[1] + b[X]) \cdot (c[1] + d[X]) &= ac[1] + bd[X^2] + ad[X] + bc[X] \\ &= (ac - bd)[1] + (ad + bc)[X] \end{aligned}$$

Therefore, $\mathbb{R}[X]_{X^2+1}$ is isomorphic to \mathbb{C} .

Definition 22. A field K is algebraically closed, if every nonconstant polynomial with coefficients in K has a root in K.

Theorem 23. Every field J has an algebraic closure, i.e. a field extension K that is algebraically closed.

For us, it is important to know the

Theorem 24. (Fundamental Theorem of Algebra) \mathbb{C} is the algebraic closure of \mathbb{R} .

3 Greatest common divisors

Definition 25. For $a, b \in R$, R an integral domain, $d \in R$ is called a greatest common divisor of a and b, d = gcd(a, b), if d divides a and b, and every $t \in R$ dividing a and b divides d, too.

If a gcd(a, b) exists, it is unique up to units, and thus it makes sense to speak of *the gcd* of *a* and *b*.

3.1 GCD over fields

Theorem 26. Let K be a field, and $P_1(X)$, $P_2(X) \neq 0$ polynomials from K[X]. Then there exists $gcd(P_1(X), P_2(X)) \in K[X]$, and there are $A(X), B(X) \in K[X]$, with $deg(A(X)) < deg(P_2(X))$ and $deg(B(X)) < deg(P_1(X))$ with

$$gcd(P_1(X), P_2(X)) = A(X) \cdot P_1(X) + B(X) \cdot P_2(X).$$

Proof. We construct both $gcd(P_1(X), P_2(X))$ and A(X), B(X) by the extended Euclidean Algorithm over a field.

$$\begin{split} & [A(X), B(X)] := [1, 0] \\ & [a(X), b(X)] := [0, 1] \\ & \underline{\text{while}} \ P_2(X) \neq 0 \ \underline{\text{do}} \\ & [Q(X), R(X)] := [quo(P_1(X), P_2(X)), rem(P_1(X), P_2(X))] \\ & [P_1(X), P_2(X)] := [P_2(X), R(X)] \\ & [A(X), a(X)] := [a(X), A(X) - Q(X)a(X)] \\ & [B(X), b(X)] := [b(X), B(X) - Q(X)b(X)] \\ & \underline{\text{od}} \\ & \underline{\text{return}} \ [P_1(X), A(X), B(X)] \end{split}$$

3.2 GCD over \mathbb{Z}

Polynomial division in the Euclidean algorithm works, because $lc(P_2(X))$ is a unit throughout the algorithm, because K is a field. From now on, we consider Polynomials over \mathbb{Z} , and the Euclidean algorithm will not work in general. Let $P_1(X) = \sum_{i=0}^{m} a_i X^i$, $P_2(X) = \sum_{j=0}^{n} b_j X^j \neq 0$, $m \geq n$. For a pseudodivision in $\mathbb{Z}[X]$, premultiply $P_1(X)$ by b_n^{m-n+1} , and define pseudoquotient and pseudoremainder by

$$pquo(P_1(X), P_2(X)) = quo(b_n^{m-n+1} \cdot P_1(X), P_2(X))$$
$$prem(P_1(X), P_2(X)) = rem(b_n^{m-n+1} \cdot P_1(X), P_2(X)).$$

Definition 27. For $P(X) \in \mathbb{Z}[X]$, define the content cont(P(X)) as gcd of the coefficients of P(X), and the primitive part $pp(P(X)) = \frac{P(X)}{cont(P(X))}$.

Theorem 28. $\mathbb{Z}[X]$ is a unique factorization domain, and therefore, a gcd exists for all pairs of nonzero Polynomials over Z.

Proof. A proof that $\mathbb{Z}[X]$ is a *UFD* is to long for this paper, but at least, it is easy to derive a formula for the *gcd* on *UFD*'s.

For $P_1(X), P_2(X) \in \mathbb{Z}[X]$, we have

 $cont(gcd(P_1(X), P_2(X))) = gcd(cont(P_1(X)), cont(P_2(X)))$ $pp(gcd(P_1(X), P_2(X))) = gcd(pp(P_1(X)), pp(P_2(X))).$

Using polynomial pseudodivion instead of polynomial division in the Euclidean algorithm, we can find the gcd for two nonzero polynomials over \mathbb{Z} : Generalized Euclidean Algorithm
$$\begin{split} c &:= gcd(cont(P_1(X)), cont(P_2(X)))\\ & [P_1(X), P_2(X)] := [pp(P_1(X)), pp(P_2(X))]\\ & \underline{while} \ P_2(X) \neq 0 \ \underline{do}\\ & [P_1(X), P_2(X)] := [P_2(X), prem(P_1(X), P_2(X))]\\ & \underline{od}\\ & \underline{return} \ c \cdot pp(P_1(X))\\ & Example \ 29. \ P_1(X) = X^3 - 2X^2 + 3 + 1, \ P_2(X) = 2X^2 + 1\\ & 2^2 \cdot (X^3 - 2X^2 + 3 + 1) = (2X - 4) \cdot (2X^2 + 1) + (10X + 8) \end{split}$$

$$10^{2} \cdot (2X^{2} + 1) = (20X - 16) \cdot (10X + 8) + 228$$
$$228^{2} \cdot (10X - 8) = (2280X - 1824) \cdot 228 + 0$$

 $gcd(cont(P_1(X)), cont(P_2(X))) = 1$, and therefore, $gcd(P_1(X), P_2(X)) = 1$. Premultiplication leads to an exponential growth of coefficients, the greatest number in our calculation was 519840.

One possiblility to reduce the the coefficient growth, is to divide every pseudoremainder by its content. The problem is, that we would have to do a gcd calculation in \mathbb{Z} at every step of our algorithm. Before we go on with gcd computations, we ask what it means, if two Polynomials in $\mathbb{Z}[X]$ have a common root in \mathbb{C} .

3.3 Resultants

Definition 30. For two Polynomials $P_1(X) = \sum_{j=0}^m a_j X^j$, $P_2(X) = \sum_{k=0}^n b_k X^k$ in $\mathbb{Z}[X]$, we define the resultant

$$res[P_1(X), P_2(X)] := a_m^n b_n^m \prod_{j=0}^m \prod_{k=0}^n (\alpha_j - \beta_k).$$

where α_j are the roots of P_1 , β_k of P_2 .

Theorem 31. 1. $res[P_1(X), P_2(X)] = 0$ if $P_1(X)$ and $P_2(X)$ have a common root.

2. $res[P_1(X), P_2(X)] = (-1)^{mn} b_n^m \prod_{k=1}^n P_1(\beta_k) = a_m^n \prod_{j=1}^m P_2(\alpha_j)$

Proof. 1. Obvious.

2. Write, for example, $P_1(X)$ as a product of linear factors.



The Matrix is $(m+n) \times (m+n)$ and contains n "a" rows and m "b" rows.

Proof.

Consider the polynomial

$$q(\lambda) := det \begin{pmatrix} a_m & \cdots & \cdots & a_0 - \lambda & \mathbf{0} \\ & \ddots & & & \ddots & \\ \mathbf{0} & a_m & \cdots & \cdots & a_0 - \lambda \\ & b_n & \cdots & \cdots & b_0 & \\ & & & \mathbf{0} & \\ & & & & \ddots & \\ & \mathbf{0} & & & \\ & & & & b_n & \cdots & \cdots & b_n \end{pmatrix} ,$$

and assume the simple case, that $P_2(X)$ has only single roots β_i , and that all $P_1(\beta_i)$ are different. Then, for all $1 \leq i \leq n$, $\lambda = P_1(\beta_i)$ is a root of $q(\lambda)$, and because $q(\lambda)$ has at most *n* different roots, $P_1(\beta_i)$ are all roots. Defining $q_n = lc(q(\lambda))$ and $q_0 = q(0)$, we have:

$$(-1)^n q_n \prod_{k=1}^n P_1(\beta_k) = q_0.$$

And, by the structure of the matrix:

$$q(\lambda) = (-1)^{mn} b_n^m \cdot (-\lambda)^n + \dots$$

Therefore,

$$(-1)^{mn}b_n^m \prod_{k=1}^n P_1(\beta_k) = q_0.$$

Now, we can find the elements of the pseudoremainder sequence by calculating special subdeterminants of this matrix, so called subresultants.

There is no time to derive this, but this is the Sylvester-Habicht Method for pseudoremainders:

Instead of

$$(lc(P_{i+1}(X)))^{n_i-n_i+1+1}P_i(X) = P_{i+1}(X)Q_i(X) + P_{i+2}(X),$$

calculate

$$(lc(P_{i+1}(X)))^{n_i-n_i+1+1}P_i(X) = P_{i+1}(X)Q_i(X) + \beta_i P_{i+2}(X).$$

Where

$$\beta_1 = (-1)^{n_1 - n_2 + 1}, \ \beta_i = (-1)^{n_i - n_{i+1} + 1} lc(P_i(X)) \cdot H_i^{n_i - n_{i+1}},$$

and

$$H_2 = (lc(P_2(X))^{n_1 - n_2}, H_i = (lc(P_i(X))^{n_{i-1} - n_i} H_{i-1}^{1 + n_i - n_{i-1}}).$$

4 Real roots

Now we will consider the real roots of polynomials in $\mathbb{Z}[X]$. We are interested in methods to count them, in order to isolate and finally approximate them.

4.1 Root counting and isolation with Fourier's and Sturm's theorems

Theorem 33. Let p(x) be a polynomial in $\mathbb{R}[x]$. Then, for a real root y of multiplicity m, we have, that the sequence

$$[p(y-\epsilon), p'(y-\epsilon), ..., p^{(m)}(y-\epsilon)]$$

has alternating sign, while the elements of

$$[p(y+\epsilon), p'(y+\epsilon), ..., p^{(m)}(y+\epsilon)]$$

have the same sign, for ϵ sufficiently small.

Proof. Apply Taylors theorem to all $p^{(k)}(y \pm \epsilon)$ up to the first non-vanishing order.

Definition 34. For a polynomial p(x), with n = deg(p(x)) > 0, the Fourier sequence is defined as $fseq(x) := [p(x), p^{(1)}(x), ..., p^{(n)}(x)]$.

Definition 35. For a sequence of real numbers $S = [a_0, ..., a_n]$, we say that there is a sign variation between a_i and a_j , if a_i and a_j have opposite sign, and all members between (if there are any) are zero.

The number of sign variations is denoted by Var(S).

Theorem 36. (Fourier) For real numbers a < b, we have: The number N of roots in (a, b], counting multiplicities is bounded by:

$$N = V(fseq(a)) - V(fseq(b)) - 2 \cdot \lambda, \lambda \ge 0.$$

Proof. fseq(x) can only lose sign variations when x "passes by" a root of p(x) or one of the derivatives. Show that fseq(x) loses m sign variations at roots of p(x) with multiplicity m, and that it loses an even number of variations at roots of the derivatives.

With his theorem, Fourier could only give an upper bound. Sturm gave a method for exact counting:

Definition 37. For $p(x) \in \mathbb{R}[x]$ a generalized Sturm sequence is a sequence of polynomials $gsseq(x) := [p(x), p_1(x), ..., p_{k+1}(x)]$, so that:

- In a sufficiently small neighbourhood of every zero y of p(x), p(x) and $p_1(x)$ have opposite signs for x < y, and same signs for $x \ge y$.
- Consecutive members do not vanish simultaneously.

- The two neighbours of a vanishing member have opposite sign.
- $p_{k+1}(x)$ has no real roots, and thus always the same sign.

For p(x) without multiple roots in \mathbb{R} , one possible gsseq is

$$sseq(x) = [p(x), p'(x), r_1(x), ..., r_k(x)]$$

with

$$r_{j-2}(x) := r_{j-1}(x)q_k(x) - r_j(x).$$

Theorem 38. (Sturm) For real numbers a < b, we have:

$$|\{a < x \le b : p(x) = 0\}| = V(gsseq(a)) - V(gsseq(b)).$$

Proof. Show that gsseq loses exactly one sign variation at roots of p(x) and no sign variation at roots of the other members.

Now we also have a method for counting the complex roots of p(x):

Theorem 39. Let p(x) be a polynomial of degree n, and let gsseq(x) be a complete sequence (i.e. it contains n + 1 members). Then p(x) has as many pairs of complex roots as there are sign variations in the sequence of leading coefficients in gsseq(x).

Proof. "Evaluate" gsseq(x) at $-\infty$ and $+\infty$.

Sturms theorem seems insufficient, because it only treats polynomials with single roots. But there is an algorithm that gives us the squarefree factorization of a polynomial over an integral domain.

Next we compute an upper bound for the positive roots of a polynomial.

Theorem 40. (Cauchy) If $p(x) = \sum_{j=0}^{n} c_j x^j$ with $c_n > 0$ has got $\lambda \ge 0$ negative coefficients,

$$b := \max_{\{1 \le k < n: c_{n-k} < 0\}} \{ |\frac{\lambda c_{n-k}}{c_n}|^{\frac{1}{k}} \}$$

is an upper bound for the positive roots of p(x).

Proof. Verify that

$$\sum_{\{1 \le k < n: c_{n-k} < 0\}} |c_{n-k}| b^{n-k} \le c_n b^n.$$

An algorithm for b will not really calculate k-th roots. Instead, it will calculate a power of 2 that is a bound for b.

Now, we are ready to understand Sturms Bisection algorithm for isolation of real roots. For $p(x) \in \mathbb{Z}[x]$ with only single roots the algorithm will

• determine, whether 0 is a root,

- calculate a bound on the positive roots, obtain isolation intervals using bisection and Sturms theorem,
- do the same for the negative roots.

Without a derivation: The Sturm bisection method is performed in $O(n^7 L^3[|p(x)|_{\infty}])$, where $L[m] := \lfloor log_2(|m|) \rfloor + 1$.

Example 41. For $p(x) = x^3 + 2x^2 - x - 2$ we have: $sseq(x) = [x^3 + 2x^2 - x - 2, 3x^2 + 4x - 1, 7x + 8, 1]$.

 $b_p = 2$ is a bound for positive roots, $b_n = -4$ is a bound for negative roots. The algorithm directly finds the root -2, and returns (-2, 0) and (0, 2) as isolation intervals for the roots -1 and 1.

4.2 Root isolation with continued fractions

Theorem 42. (Budan, equivalent to Fourier) Let a < b be real and consider $p(x) \in \mathbb{R}[x]$. The number of roots that p(x) has in (a, b] is never greater than the loss of sign variations in the coefficient sequence of p(x + b) compared to p(x + a).

Proof. When can the number of sign variations in the coefficient sequence of p(x+a) change?

Definition 43. For a nonsingular matrix $\mathbf{M} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, define the Möbius substitution by $y := \mathbf{M}(x) = \frac{a \cdot x + b}{c \cdot x + d}$.

Note that composition of substitutions is described by multiplication of the matrices, and that these matrices form a group.

Theorem 44. For a polynomial p(x) with rational coefficients and without multiple roots, and for $a_1 \ge 0$, $a_i > 0, i > 1$ there is always $m \in \mathbb{N}$ and the corresponding transformation



so that the transformed polynomial $p_{ti}(y)$ has at most one sign variation in its coefficient sequence.

For this theorem (and some other), a proof is omitted because it would be to long and lead to far away from the main topic of root isolation. For an understanding, why the isolation algorithm might work as it should, this theorem is enough.

The continued fraction transformation can be written as Möbius substitution:

$$x = \begin{bmatrix} a_1 & 1 \\ 1 & 0 \end{bmatrix} \cdots \begin{bmatrix} a_m & 1 \\ 1 & 0 \end{bmatrix} (y).$$

Theorem 45. (Cardano-Descartes) A polynomial with no or exactly one sign variation in its coefficient sequence has no or exactly one positive root, respectively.

Proof. Evaluate fseq(x) at 0 and ∞ .

The continued fraction isolation algorithm returns isolation intervals for polynomials p(x) in $\mathbb{Z}[x]$ without multiple roots. It will:

- Calculate lower bounds for the positive zeroes of p(x) and transformed polynomials.
- Use Möbius substitutions to transform every positive root of p(x) to the only positive root of some $p_{ti}(y)$, and calculate isolation intervals from the transformation formula.
- Treat the negative roots in the same way by substituting $p(x) := \pm p(-x)$.

Complexity: $O(n^5 L^3[|p(x)|_{\infty}]).$

4.3 Root approximation by bisection

Now we are left with a single root of p(x) inside an open isolation interval (a, b). To approximate it with a precision of ϵ , we can use the bisection algorithm.

4.4 Root approximation by continued fractions

If the root was isolated by the continued fraction method, we already know a transformation $x = \mathbf{M}(y)$ and a polynomial $p_M(y)$ which has only one positive root. Then our algorithm looks like this:

- 1. Compute the integer part a of the positive root of $p_M(y)$.
- 2. Update $p_M(y) := p_M(y+a)$ and $\mathbf{M}(y) := \mathbf{M}(y+a)$.

- 3. Test, whether $p_M(0) = 0$. Then <u>return</u> $\frac{M_{12}}{M_{22}}$ as exact value for the root.
- 4. Test, whether $\left|\frac{M_{11}}{M_{21}} \frac{M_{12}}{M_{22}}\right| \le \epsilon$. If so, <u>return</u> $\left(\frac{M_{11}}{M_{21}}, \frac{M_{12}}{M_{22}}\right)$.
- 5. Set $p_M(y) := p_M(\frac{1}{y})$ and $\mathbf{M}(y) := \mathbf{M}(\frac{1}{y})$, and return to 1.