JASS 2005

Computation of heat conduction ...



... within ceramic blocks



• Modelling:

from nature to mathematics

• Simulation:

solution of the mathematical problem by finite elements and multigrid method

• Visualization of the results:

pictures of isothermal lines, temperature distribution and heat flow vectors



What is heat conduction?



heat conduction: diffusive transport of energy in solids, liquids and gases, caused by Brownian motion of atoms and molecules





The amount Q of transferred heat is proportional to:

- temperature difference T_1 - T_2
- cross-sectional area A
- period of time Δt
- inverse thickness $1 / \Delta x$

$$\Rightarrow Q = \lambda \frac{T_1 - T_2}{\Delta x} A \Delta t$$

The coefficient λ is called **thermal conductivity** and strongly depends on the material.

Fourier's law (continued)



$$Q = \lambda \frac{T_1 - T_2}{\Delta x} A \Delta t$$

Because of [Q] = Joule = Watt sec, [T] = Kelvinthe unit of the thermal conductivity λ has to be W/(mK).

material	thermal conductivity
gold	295 W/(mK)
aluminium	230 W/(mK)
glass	1.4 W/(mK)
H ₂ O	0.6 W/(mK)
air	0.025 W/(mK)

Fourier's law (continued)



transferred heat with respect to time

$$heatflow: \qquad \dot{Q} = \frac{dQ}{dt} = \lambda \frac{T_1 - T_2}{\Delta x} A \quad [W]$$

transferred heat with respect to time and area

$$heatflux: \qquad \dot{q} = \frac{\dot{Q}}{A} = \lambda \frac{T_1 - T_2}{\Delta x} \quad [\frac{W}{m^2}]$$

In the limit $\Delta x \rightarrow 0$, we obtain Fourier's law:

$$\dot{q} = -\lambda \nabla T$$

Derivation of Fourier's PDE



volume element dV = dx dy dz



$$\dot{Q}(x) = \dot{q}_x \, dy \, dz,$$

$$\dot{Q}(x + dx) = (\dot{q}_x + \frac{\partial \dot{q}_x}{\partial x} dx) \, dy \, dz$$

Net heat entry by x-direction: $\dot{Q}(x) - \dot{Q}(x + dx) = -\frac{\partial \dot{q}_x}{\partial x} dx dy dz$

y- and z-direction accordingly: $-\frac{\partial \dot{q}_y}{\partial y} dx \, dy \, dz, \quad -\frac{\partial \dot{q}_z}{\partial z} dx \, dy \, dz$

Under steady-state conditions, the sum of all three must vanish:

$$-\frac{\partial \dot{q}_x}{\partial x} - \frac{\partial \dot{q}_y}{\partial y} - \frac{\partial \dot{q}_z}{\partial z} = 0$$

Fourier's PDE (continued)



 $-\frac{\partial \dot{q}_x}{\partial x} - \frac{\partial \dot{q}_y}{\partial y} - \frac{\partial \dot{q}_z}{\partial z} = 0$ $\begin{cases} \text{remember Fourier's law:} \\ \dot{q}_x = -\lambda \frac{\partial T}{\partial x}, \quad \dot{q}_y = -\lambda \frac{\partial T}{\partial y}, \quad \dot{q}_z = -\lambda \frac{\partial T}{\partial z} \end{cases}$ $\frac{\partial}{\partial x}(\lambda \frac{\partial T}{\partial x}) + \frac{\partial}{\partial y}(\lambda \frac{\partial T}{\partial y}) + \frac{\partial}{\partial z}(\lambda \frac{\partial T}{\partial z}) = 0$ $div(\lambda \nabla T) = 0$ or simply:



Boundary conditions ...

... of 1^{st} type (Dirichlet) temperature given: $T = T_b$

... of 2nd type (Neumann) **heat flux** given: $\dot{q}_b = -\lambda \frac{\partial T}{\partial n}$

... of 3rd type (mixed / Cauchy) coupling of convection (+ radiation) and conduction

Mathematical model



PDE for steady-state conditions: $div(\lambda \nabla T) = 0$





Choosing a subspace of V



Problem: Galerkin ansatz: We choose: $dim V = \infty$ $Take \ a \ subspace \ S \le V \ with \ dim \ S < \infty$ finite element space of bilinear functions on squares

The four local shape functions on the unit square

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Element stiffness matrix A^(e)



 $A_{ij}^{(e)} = \int_{(e)} \lambda^{(e)} (\nabla \varphi_j)^T (\nabla \varphi_i) d\mathbf{x}$ $A^{(e)} = \lambda^{(e)} / 6 \begin{pmatrix} 4 & -1 & -1 & -2 \\ -1 & 4 & -2 & -1 \\ -1 & -2 & 4 & -1 \\ -2 & -1 & -1 & 4 \end{pmatrix}$

Sketch of the algorithm



Go from coarsest grid level to finest by recursively performing interpolation and adding hierarchical surpluses:



Compute the residual on finest grid level and perform one step of weighted Jacobi method: $T^{(k+1)} = T^{(k)} - \omega D^{-1} res^{(k)}$

> approximation to the solution in k-th iteration $_^{\uparrow}$ relaxation parameter $__{inverse of diagonal matrix}$

Recursively **restrict** the residual to the next coarser grid level and perform an **iteration step** there (until top level is reached).







fine grid cell $T_1, ..., T_4$: current approximation We define $T := (T_1, T_2, T_3, T_4)^T$

$$(A^{(e)}T)_i = \int_{(e)} \lambda^{(e)} (\nabla (\sum_{j=1}^4 T_j \varphi_j))^T (\nabla \varphi_i) d\mathbf{x}$$

 $(A^{(e)} T)_i$: contribution of the cell to the residual in node i



Residual assembly



A temperature node (\bullet) has four surrounding cells. Accordingly, the residual of one node is assembled by four cell residuals.



Assembled residual: net heat flow *node* → *surroundings*



$$T_i^{(k+1)} = T_i^{(k)} - \omega D_i^{-1} \operatorname{res}_i^{(k)}$$

where $D_i = 2/3 (\lambda_a + \lambda_b + \lambda_c + \lambda_d)$



if $(res_i^{(k)} = 0)$ no correction

if $(res_i^{(k)} > 0)$ decrease temperature if $(res_i^{(k)} < 0)$ increase temperature



Correction on coarser grids



Remember the weighted Jacobi method: $T_i^{(k+1)} = T_i^{(k)} - \omega D_i^{-1} res_i^{(k)}$

 $res_i^{(k)}$:obtained by restriction D_i^{-1} :In general, coarse grid cellsconsist of fine grid cells withdifferent thermal conductivities.



<u>Problem:</u> how to compute D